

GEORGIA INSTITUTE OF TECHNOLOGY
SCHOOL OF ELECTRICAL AND COMPUTER ENGINEERING

ECE 2026 — Summer 2018
Final Exam

July 27, 2018

NAME: _____

Important Notes:

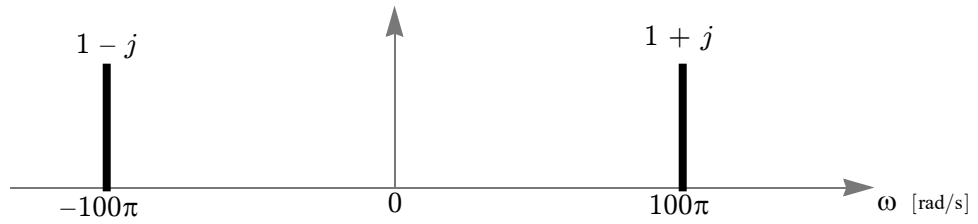
- Do not unstaple the test.
- Closed book and notes, except for three double-sided pages (8.5" × 11") of hand-written notes.
- Calculators are allowed, but no smartphones/WiFi/etc.
- JUSTIFY your reasoning CLEARLY to receive partial credit.
- Express all angles as a fraction of π . For example, write 0.1π as opposed to 18° or 0.3142 radians.
- You must write your answer in the space provided on the exam paper itself.
Only these answers will be graded. Circle your answers, or write them in the boxes provided.
If more space is needed for scratch work, use the backs of the previous pages.

Problem	Points	Score
1	10	
2	15	
3	15	
4	15	
5	15	
6	10	
7	20	
TOTAL:	100	

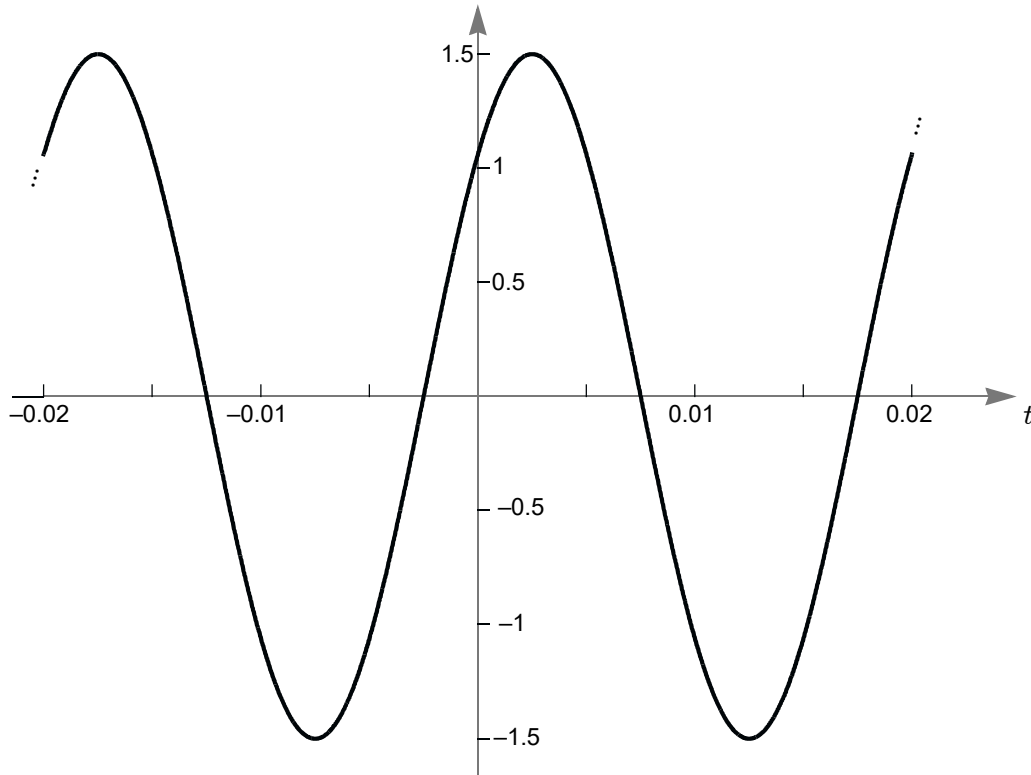
PROB. Su18-Fin.1.

Let $x_1(t) = 2\cos(100\pi(t - 0.002))$.

Let $x_2(t)$ be the signal whose spectrum is shown below:



Let $x_3(t)$ be the sinusoidal signal sketched below:

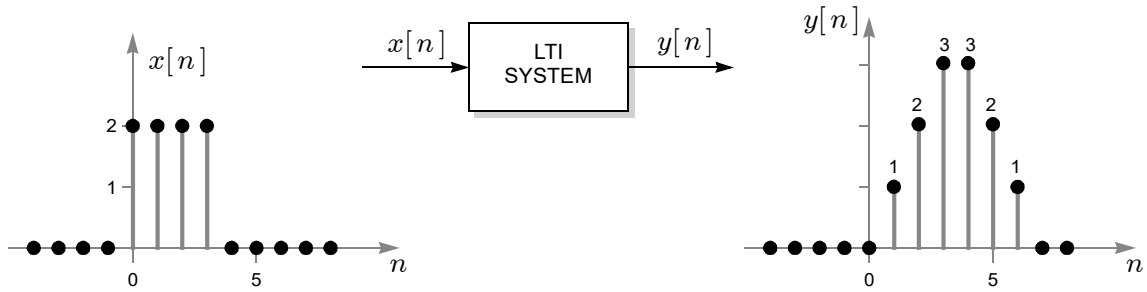


The *sum* of these three signals can be written as $x_1(t) + x_2(t) + x_3(t) = A\cos(100\pi t + \varphi)$,

where $A = \boxed{}$ and $\varphi = \boxed{}$.

PROB. Su18-Fin.2.

Suppose the output of a linear and time-invariant discrete-time filter in response to a finite-length input of $x[n] = \{\dots 0 0 \underline{2} 2 2 2 0 0 \dots\}$ is $y[n] = \{\dots 0 0 \underline{1} 2 3 3 2 1 0 0 \dots\}$, as shown below:

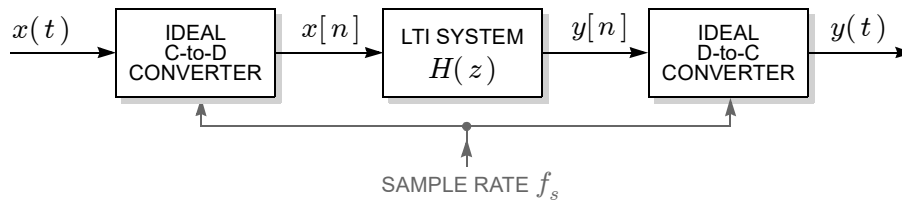


The filter's impulse response $h[n]$ has values:

$$h[0] = \boxed{}, \quad h[1] = \boxed{}, \quad h[2] = \boxed{}, \quad h[3] = \boxed{}, \quad h[4] = \boxed{}$$

PROB. Su18-Fin.3.

Consider the following system in which a continuous-time input $x(t)$ is sampled, producing $x[n]$, then filtered, producing $y[n]$, and finally converted back to continuous time, yielding an overall output $y(t)$:



The system function of the discrete-time LTI system is $H(z) = 1 - z^{-1} + z^{-2}$.

(a) Which of the plots (A... H) on the next page shows the magnitude response of this filter?

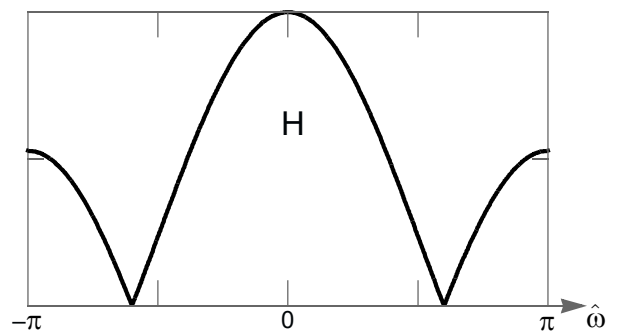
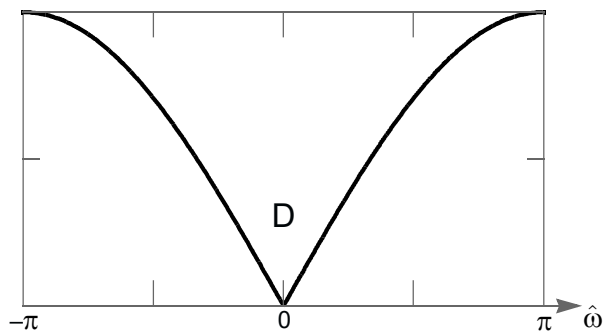
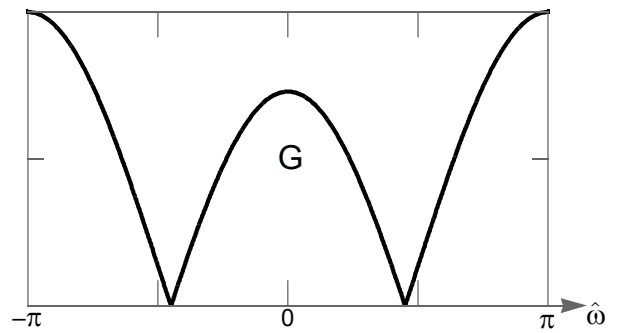
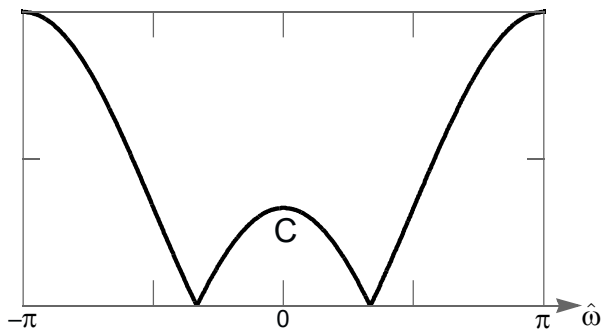
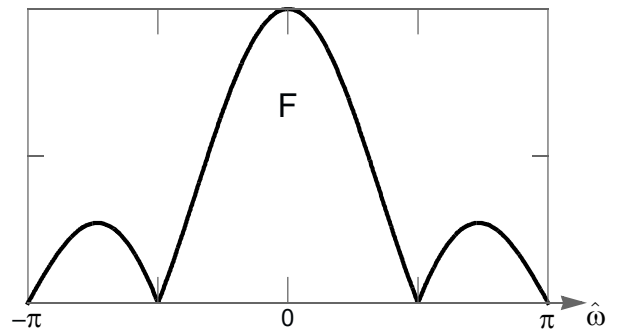
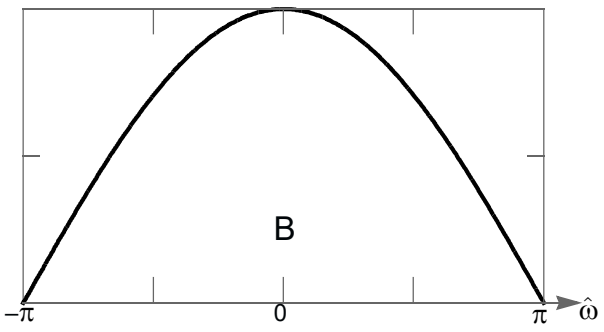
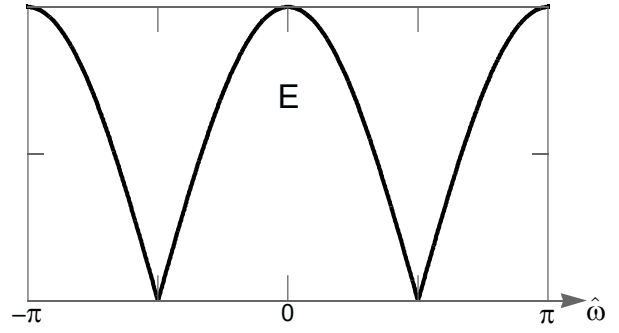
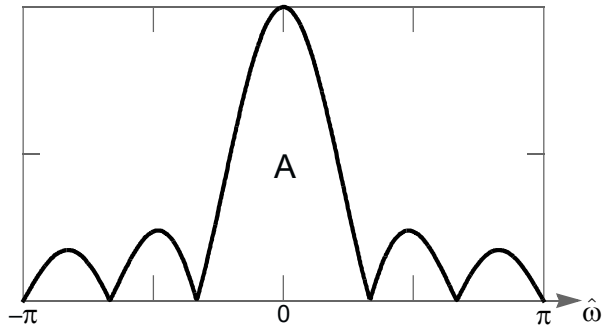
(b) A *constant* input $x(t) = 1$ (for all t) will result in the *constant* output $y(t) =$

(for all t).

(c) Specify a sample rate $f_s =$

samples/s

so that a C-to-D input of $x(t) = \cos(10\pi t) + \cos(14\pi t)$ results in a *zero* output, $y(t) = 0$ (for all t).



PROB. Su18-Fin.4.

Consider an FIR filter whose difference equation is:

$$y[n] = (1 + \beta)x[n] + (1 - \beta)x[n - 1],$$

where β is an unspecified real constant.

If the output of this system in response to the sinusoidal input $x[n] = \cos(0.7\pi n)$

is

$$y[n] = \cos(0.7\pi n + \theta),$$

then it must be that $\beta =$

and

$\theta =$

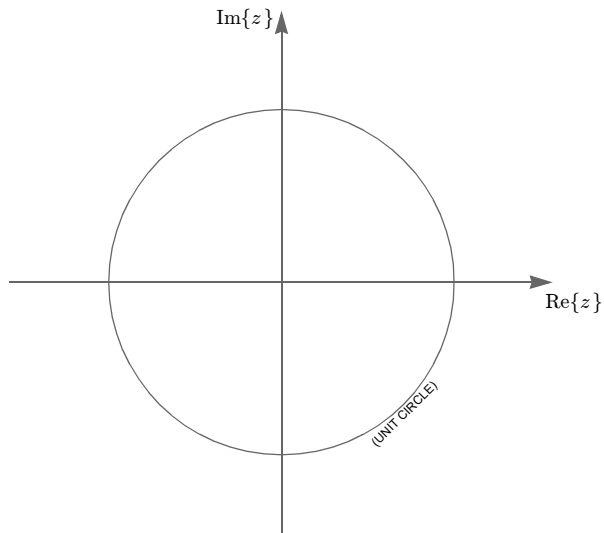
PROB. Su18-Fin.5. Consider an LTI system described by the recursive difference equation:

$$y[n] = x[n] - 0.2y[n - 1].$$

(a) The system is [IIR] [FIR] (circle one).

(b) The system transfer function is $H(z) =$

(c) Sketch below the pole-zero plot for $H(z)$, carefully labeling the locations of all zeros and poles:



(d) If the output of this system in response to the input

$$x[n] = 10\delta[n] + B\delta[n - 1] \quad \text{is} \quad y[n] = 10\delta[n]$$

(or in other words, as lists of numbers, the input ... 0 10 B 0 ... results in the output ... 0 10 0 ...),

then it must be that the constant B is

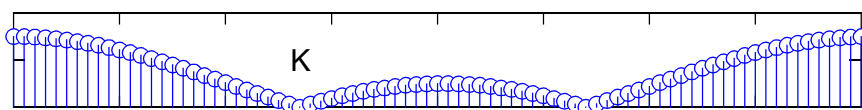
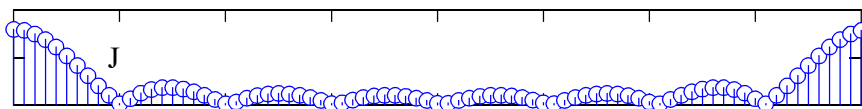
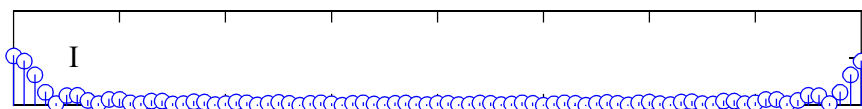
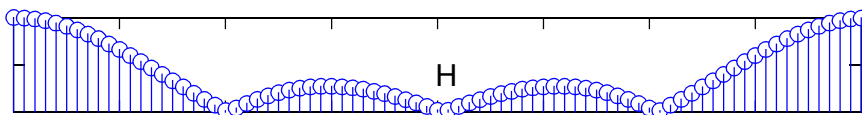
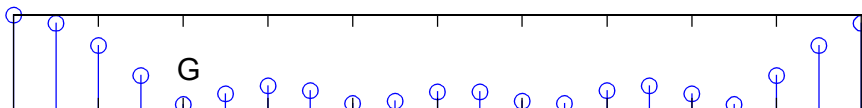
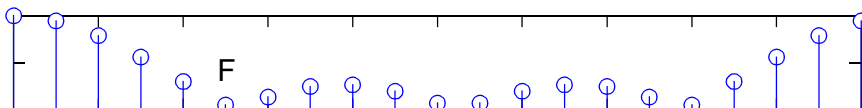
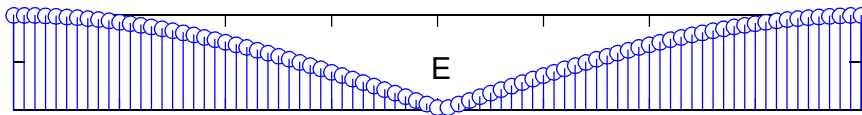
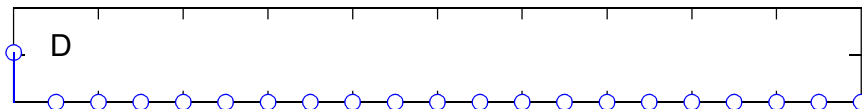
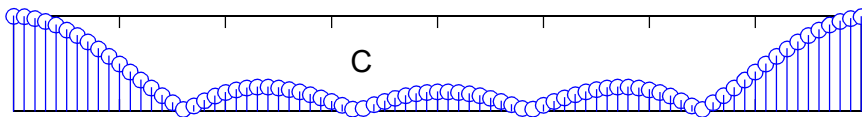
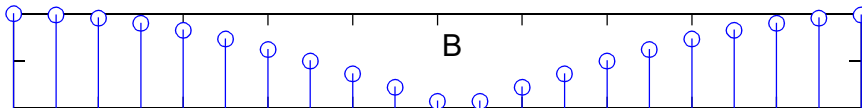
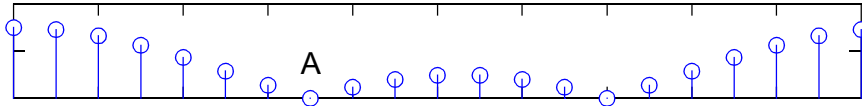
$$B =$$

PROB. Su18-Fin.6.

Shown below are eleven different outcomes that result from executing the MATLAB code:

```
stem(abs(fft(ones(1,L),N)));
```

Match each plot with the corresponding values for the variables N and L by writing a letter (A through K) in each answer box.



L = 2, N = 21

L = 2, N = 81

L = 3, N = 21

L = 3, N = 81

L = 4, N = 21

L = 4, N = 81

L = 5, N = 21

L = 5, N = 81

L = 8, N = 81

L = 21, N = 21

L = 21, N = 81

PROB. Su18-Fin.7. (The different parts are unrelated.)

(a) There are an infinite number of values for the delay parameter t_0 below such that:

$$\cos(100\pi t) + \cos(100\pi(t - t_0)) + \cos(100\pi(t - 2t_0)) = 0, \quad \text{for all time } t.$$

Name any two, both positive:

$$t_0 = \boxed{},$$

or

$$t_0 = \boxed{}.$$

(b) Simplify

$$\sum_{k=-\infty}^{\infty} \frac{\sin(0.9\pi k)}{\pi k} \cdot \frac{\sin(0.75\pi(n-k))}{\pi(n-k)} = \boxed{}.$$

a function of n

- (c) The signal $x(t) = \cos(88\pi t)\cos(8\pi t) + \cos(240\pi t)$ is periodic with fundamental frequency

$$f_0 = \boxed{} \text{ Hz.}$$

- (d) If $\{X[0], \dots, X[511]\}$ are the DFT coefficients that result from taking a 512-point DFT of the length-12 signal $x[n] = [1 \ 1 \ 1 \ 2 \ 2 \ 2 \ 3 \ 3 \ 3 \ 4 \ 4 \ 4]$ for $n \in \{0, \dots, 11\}$, then find numerical values for the following two DFT coefficients:

$$X[0] = \boxed{},$$

$$X[256] = \boxed{}.$$

Table of DTFT Pairs	
Time-Domain: $x[n]$	Frequency-Domain: $X(e^{j\hat{\omega}})$
$\delta[n]$	1
$\delta[n - n_0]$	$e^{-j\hat{\omega}n_0}$
$u[n] - u[n - L]$	$\frac{\sin(\frac{1}{2}L\hat{\omega})}{\sin(\frac{1}{2}\hat{\omega})} e^{-j\hat{\omega}(L-1)/2}$
$\frac{\sin(\hat{\omega}_b n)}{\pi n}$	$u(\hat{\omega} + \hat{\omega}_b) - u(\hat{\omega} - \hat{\omega}_b) = \begin{cases} 1 & \hat{\omega} \leq \hat{\omega}_b \\ 0 & \hat{\omega}_b < \hat{\omega} \leq \pi \end{cases}$
$a^n u[n] \quad (a < 1)$	$\frac{1}{1 - ae^{-j\hat{\omega}}}$

Table of DTFT Properties		
Property Name	Time-Domain: $x[n]$	Frequency-Domain: $X(e^{j\hat{\omega}})$
Periodic in $\hat{\omega}$		$X(e^{j(\hat{\omega}+2\pi)}) = X(e^{j\hat{\omega}})$
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(e^{j\hat{\omega}}) + bX_2(e^{j\hat{\omega}})$
Conjugate Symmetry	$x[n]$ is real	$X(e^{-j\hat{\omega}}) = X^*(e^{j\hat{\omega}})$
Conjugation	$x^*[n]$	$X^*(e^{-j\hat{\omega}})$
Time-Reversal	$x[-n]$	$X(e^{-j\hat{\omega}})$
Delay (d =integer)	$x[n - d]$	$e^{-j\hat{\omega}d} X(e^{j\hat{\omega}})$
Frequency Shift	$x[n]e^{j\hat{\omega}_0 n}$	$X(e^{j(\hat{\omega}-\hat{\omega}_0)})$
Modulation	$x[n] \cos(\hat{\omega}_0 n)$	$\frac{1}{2}X(e^{j(\hat{\omega}-\hat{\omega}_0)}) + \frac{1}{2}X(e^{j(\hat{\omega}+\hat{\omega}_0)})$
Convolution	$x[n] * h[n]$	$X(e^{j\hat{\omega}})H(e^{j\hat{\omega}})$
Parseval's Theorem	$\sum_{n=-\infty}^{\infty} x[n] ^2$	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\hat{\omega}}) ^2 d\hat{\omega}$

Table of Pairs for N-point DFT	
<i>Time-Domain:</i> $x[n], \quad n = 0, 1, 2, \dots, N - 1$	<i>Frequency-Domain:</i> $X[k], \quad k = 0, 1, 2, \dots, N - 1$
If $x[n]$ is finite length, i.e., $x[n] \neq 0$ only when $n \in [0, N - 1]$ and the DTFT of $x[n]$ is $X(e^{j\hat{\omega}})$	$X[k] = X(e^{j\hat{\omega}}) \Big _{\hat{\omega}=2\pi k/N}$ (frequency sampling the DTFT)
$\delta[n]$	1
$\delta[n - n_0]$	$e^{-j(2\pi k/N)n_0}$
$e^{-j(2\pi n/N)k_0}$	$N\delta[k - k_0],$ when $k_0 \in [0, N - 1]$
$u[n] - u[n - L],$ when $L \leq N$	$\frac{\sin(\frac{1}{2}L(2\pi k/N))}{\sin(\frac{1}{2}(2\pi k/N))} e^{-j(2\pi k/N)(L-1)/2}$
$\frac{\sin(\frac{1}{2}L(2\pi n/N))}{\sin(\frac{1}{2}(2\pi n/N))} e^{j(2\pi n/N)(L-1)/2}$	$N(u[k] - u[k - L]),$ when $L \leq N$

Table of z-Transform Pairs		
<i>Signal Name</i>	<i>Time-Domain:</i> $x[n]$	<i>z-Domain:</i> $X(z)$
Impulse	$\delta[n]$	1
Shifted impulse	$\delta[n - n_0]$	z^{-n_0}
Right-sided exponential	$a^n u[n]$	$\frac{1}{1 - az^{-1}}, \quad a < 1$
Decaying cosine	$r^n \cos(\hat{\omega}_0 n) u[n]$	$\frac{1 - r \cos(\hat{\omega}_0) z^{-1}}{1 - 2r \cos(\hat{\omega}_0) z^{-1} + r^2 z^{-2}}$
Decaying sinusoid	$A r^n \cos(\hat{\omega}_0 n + \varphi) u[n]$	$A \frac{\cos(\varphi) - r \cos(\hat{\omega}_0 - \varphi) z^{-1}}{1 - 2r \cos(\hat{\omega}_0) z^{-1} + r^2 z^{-2}}$

Table of z-Transform Properties		
<i>Property Name</i>	<i>Time-Domain</i> $x[n]$	<i>z-Domain</i> $X(z)$
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$
Delay (d =integer)	$x[n - d]$	$z^{-d} X(z)$
Convolution	$x[n] * h[n]$	$X(z)H(z)$

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ANSWER KEY

NAME: _____

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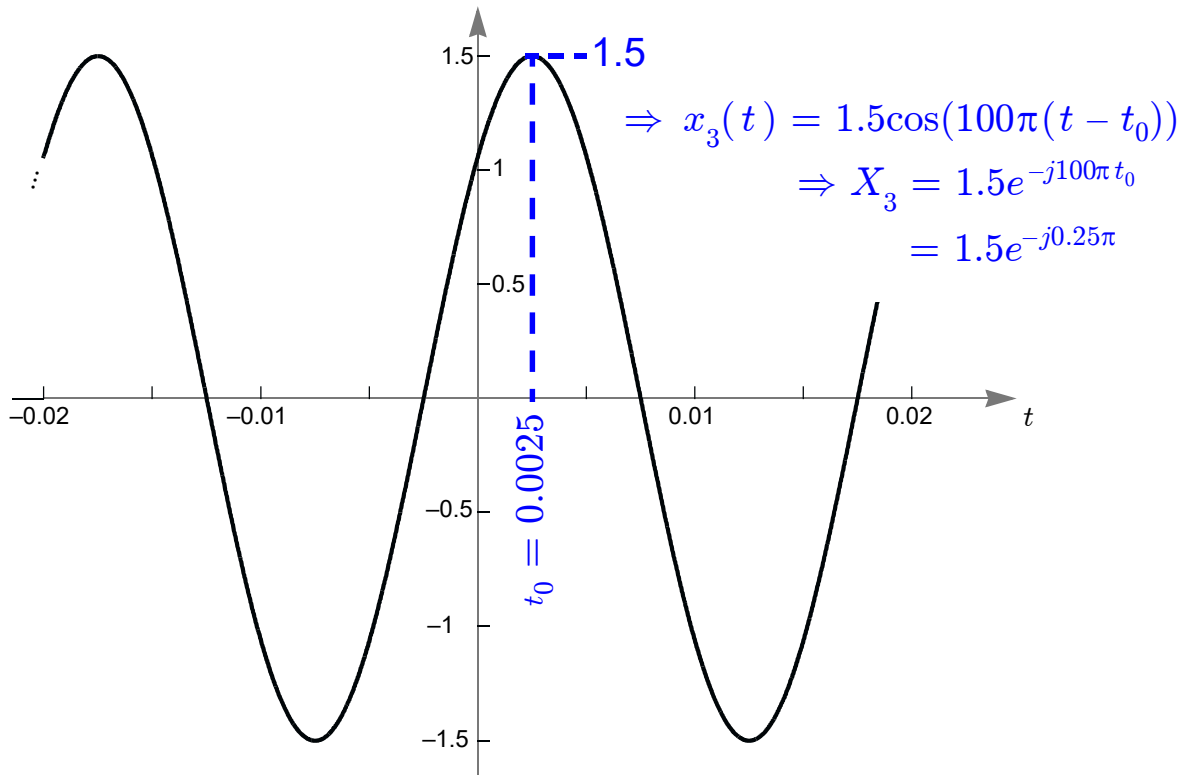
PROB. Su18-Fin.1.

Let $x_1(t) = 2\cos(100\pi(t - 0.002))$. $\Rightarrow X_1 = 2e^{-j0.2\pi}$

Let $x_2(t)$ be the signal whose spectrum is shown below:



Let $x_3(t)$ be the sinusoidal signal sketched below:



The *sum* of these three signals can be written as $x_1(t) + x_2(t) + x_3(t) = A\cos(100\pi t + \varphi)$,

where $A = \boxed{4.68}$ and $\varphi = \boxed{-0.016\pi}$.
 $(= -0.05 \text{ rads} = -2.89^\circ)$

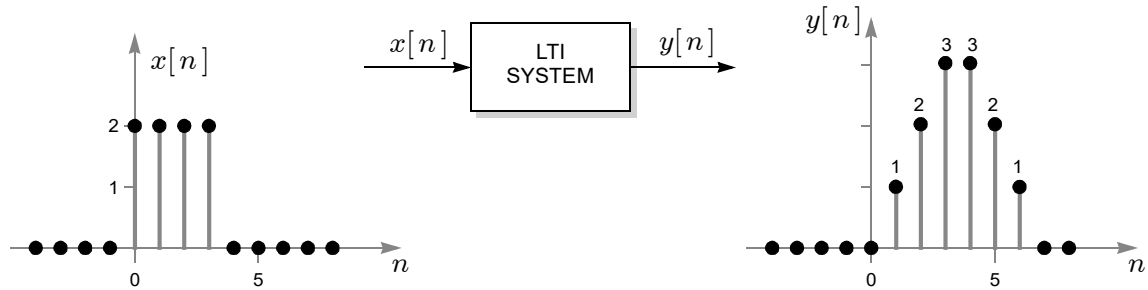
Phasor addition rule:

$$Ae^{j\varphi} = X_1 + X_2 + X_3$$

$$= 2e^{-j0.2\pi} + 2\sqrt{2}e^{j0.25\pi} + 1.5e^{-j0.25\pi} = 4.68e^{-j0.016\pi}$$

PROB. Su18-Fin.2.

Suppose the output of a linear and time-invariant discrete-time filter in response to a finite-length input of $x[n] = \{\dots 0 0 2 2 2 2 0 0 \dots\}$ is $y[n] = \{\dots 0 0 1 2 3 3 2 1 0 0 \dots\}$, as shown below:



The filter's impulse response $h[n]$ has values:

$$h[0] = \boxed{0}, \quad h[1] = \boxed{0.5}, \quad h[2] = \boxed{0.5}, \quad h[3] = \boxed{0.5}, \quad h[4] = \boxed{0}$$

$$y[n] = \sum_k h[k]x[n-k]$$

$$\text{But } y[0] = 0 \Rightarrow 0 = h[0]x[0] = 2h[0] \Rightarrow h[0] = 0$$

$$y[1] = 1 \Rightarrow 1 = h[0]x[1] + h[1]x[0] = 2h[1] \Rightarrow h[1] = 0.5$$

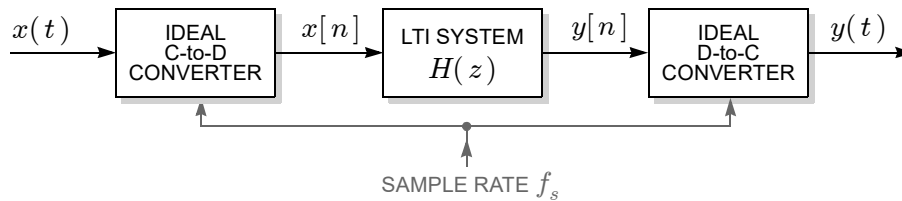
$$y[2] = 2 \Rightarrow 2 = h[0]x[2] + h[1]x[1] + h[2]x[0] = 1 + 2h[2] \Rightarrow h[2] = 0.5$$

$$y[3] = 3 = h[1]x[2] + h[2]x[1] + h[3]x[0] = 2 + 2h[3] \Rightarrow h[3] = 0.5$$

$$y[4] = 3 = h[1]x[3] + h[2]x[2] + h[3]x[1] + h[4]x[0] \Rightarrow h[4] = 0$$

PROB. Su18-Fin.3.

Consider the following system in which a continuous-time input $x(t)$ is sampled, producing $x[n]$, then filtered, producing $y[n]$, and finally converted back to continuous time, yielding an overall output $y(t)$:



The system function of the discrete-time LTI system is $H(z) = 1 - z^{-1} + z^{-2}$.

- (a) Which of the plots (A... H) on the next page shows the magnitude response of this filter?

C

Recognize this as a *nulling filter*, where $-2\cos(\hat{\omega}) = -1$
 \Rightarrow look for nulls at $\hat{\omega} = \pm\pi/3$

- (b) A *constant* input $x(t) = 1$ (for all t) will result in the *constant* output $y(t) =$ 1 (for all t).

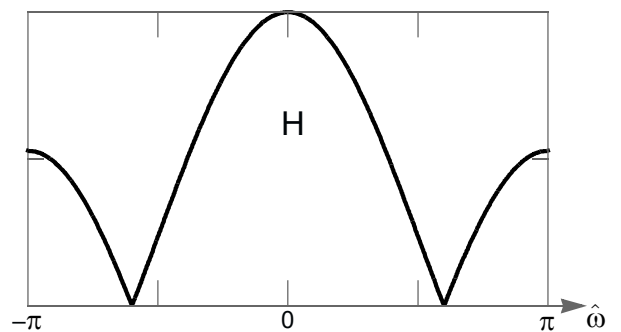
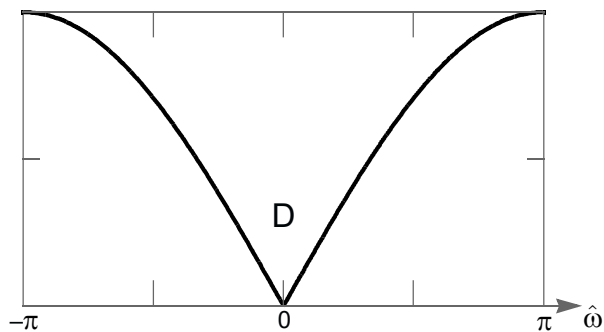
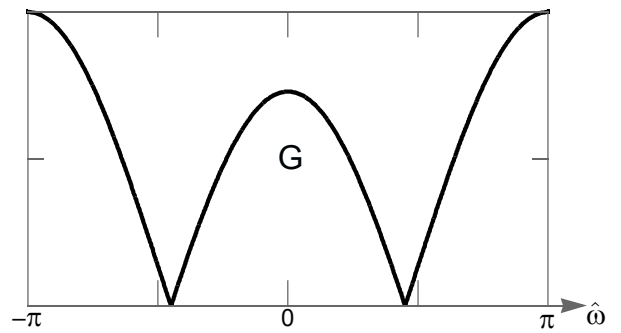
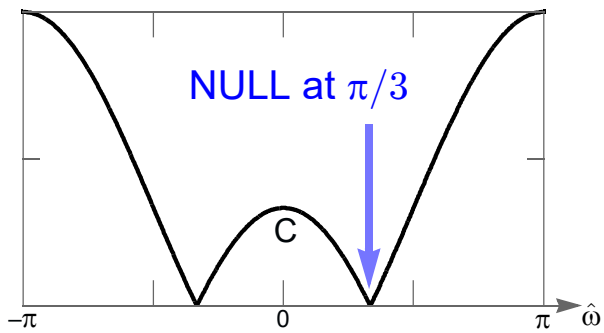
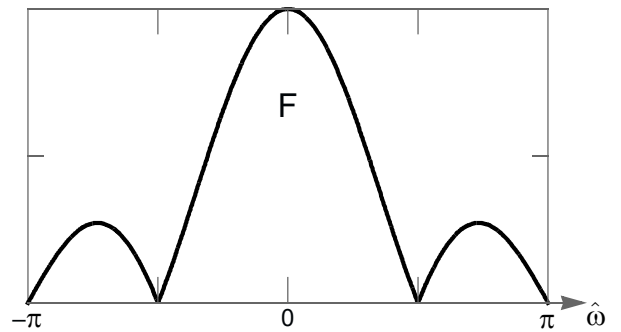
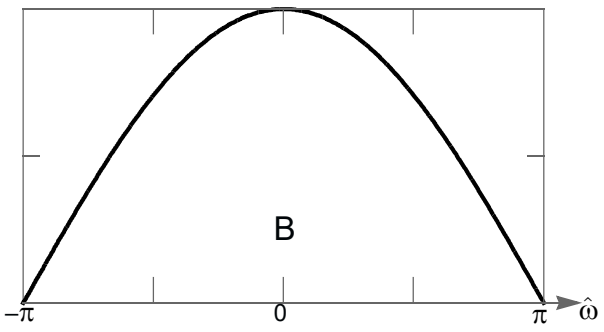
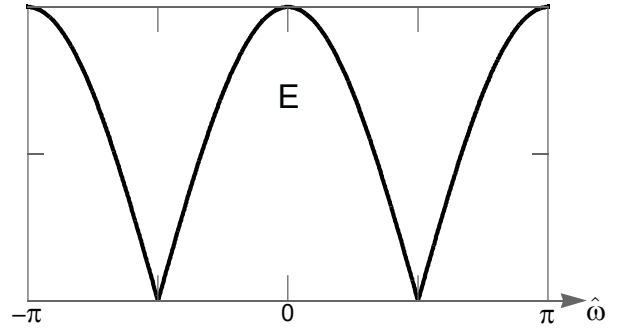
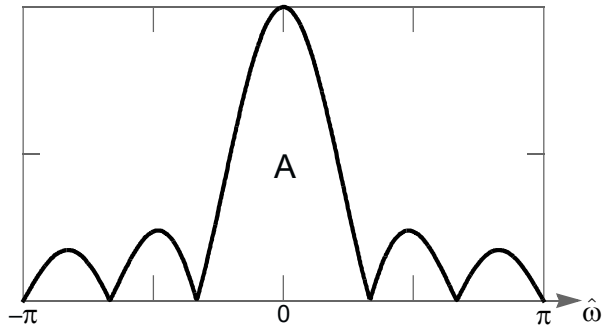
The DC gain is $b_0 + b_1 + b_2 = 1 - 1 + 1 = 1$

- (c) Specify a sample rate $f_s =$ 6 samples/s

so that a C-to-D input of $x(t) = \cos(10\pi t) + \cos(14\pi t)$ results in a *zero* output, $y(t) = 0$ (for all t).

There are an infinite number of solutions, the largest being $f_s = 6$ Hz:

$$\left. \begin{aligned} \Rightarrow \hat{\omega}_1 &= \frac{10\pi}{f_s} = \frac{5\pi}{3} = \frac{-\pi}{3} + 2\pi \\ \Rightarrow \hat{\omega}_2 &= \frac{14\pi}{f_s} = \frac{7\pi}{3} = \frac{\pi}{3} + 2\pi \end{aligned} \right\} \text{both reduce to } \hat{\omega} = \pm\pi/3 \Rightarrow \text{both nulled}$$



PROB. Su18-Fin.4.

Consider an FIR filter whose difference equation is:

$$y[n] = (1 + \beta)x[n] + (1 - \beta)x[n - 1],$$

where β is an unspecified real constant.

If the output of this system in response to the sinusoidal input $x[n] = \cos(0.7\pi n)$

is

$$y[n] = \cos(0.7\pi n + \theta),$$

then it must be that $\beta =$ **+0.2351** and $\theta =$ **-0.21 π** .

-0.2351 \leftarrow (alternative answer) \rightarrow -0.49π

The frequency response must have magnitude 1 at 0.7π

$$\begin{aligned} \Rightarrow 1 &= |H(e^{j0.7\pi})|^2 = |(1 + \beta) + (1 - \beta)e^{-j0.7\pi}|^2 \\ &= (1 + \beta)^2 + (1 - \beta)^2 + 2(1 + \beta)(1 - \beta)\cos(0.7\pi) \\ &= 2 + 2\beta^2 + 2(1 - \beta^2)\cos(0.7\pi) \end{aligned}$$

$$\Rightarrow \beta^2 = \frac{-1 - 2\cos(0.7\pi)}{2 - 2\cos(0.7\pi)} = 0.0553 \quad \Rightarrow \beta = \pm 0.2351$$

With $\beta = +0.2351$, the frequency response simplifies to

$$\begin{aligned} H(e^{j0.7\pi}) &= (1 + \beta) + (1 - \beta)e^{-j0.7\pi} \\ &= 1.2351 + 0.7649e^{-j0.7\pi} = e^{-j0.2124\pi} \end{aligned}$$

Alternative answer: With $\beta = -0.2351$, the frequency response simplifies to

$$\begin{aligned} H(e^{j0.7\pi}) &= (1 + \beta) + (1 - \beta)e^{-j0.7\pi} \\ &= 0.7649 - 1.2351e^{-j0.7\pi} = e^{-j0.4876\pi} \end{aligned}$$

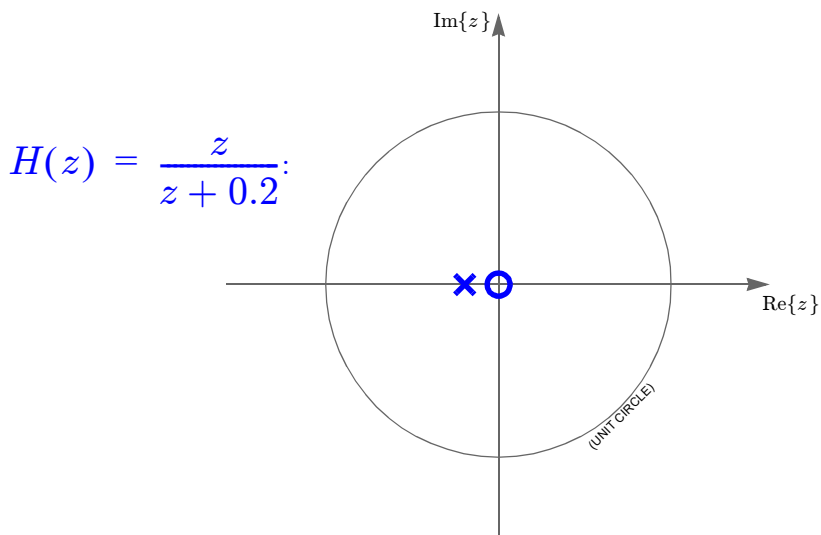
PROB. Su18-Fin.5. Consider an LTI system described by the recursive difference equation:

$$y[n] = x[n] - 0.2y[n - 1].$$

(a) The system is IIR FIR (circle one).

(b) The system transfer function is $H(z) = \frac{1}{1 + 0.2z^{-1}}$.

(c) Sketch below the pole-zero plot for $H(z)$, carefully labeling the locations of all zeros and poles:



(d) If the output of this system in response to the input

$$x[n] = 10\delta[n] + B\delta[n - 1] \quad \text{is} \quad y[n] = 10\delta[n]$$

(or in other words, as lists of numbers, the input ... 0 10 B 0 ... results in the output ... 0 10 0 ...),

then it must be that the constant B is

$$B = \frac{\quad}{\quad} = 2.$$

$$Y(z) = X(z)H(z) = (10 + Bz^{-1}) \frac{1}{1 + 0.2z^{-1}} = 10 \left(\frac{1 + \frac{B}{10}z^{-1}}{1 + 0.2z^{-1}} \right)$$

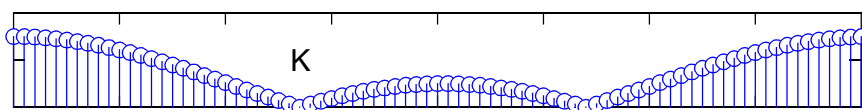
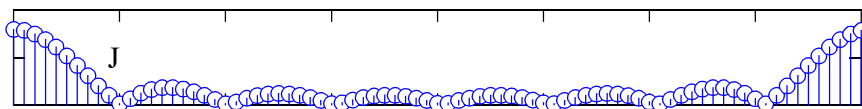
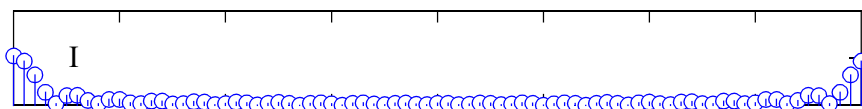
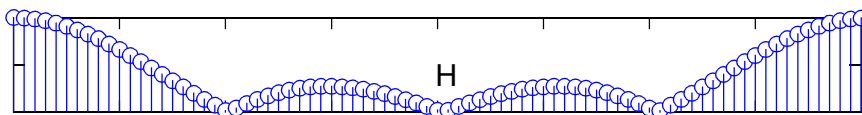
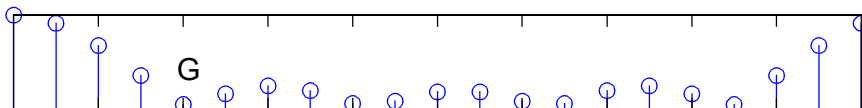
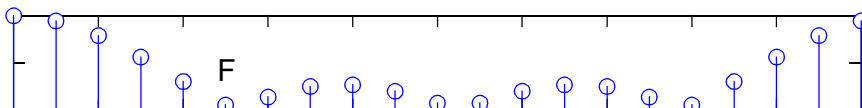
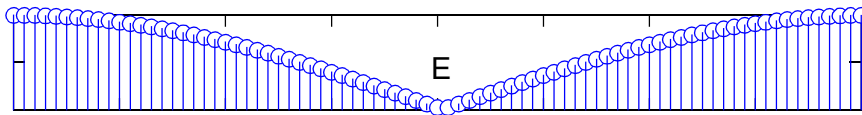
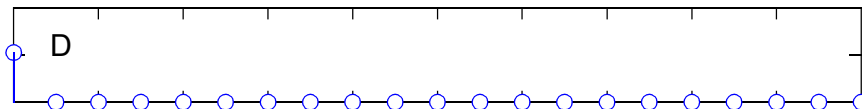
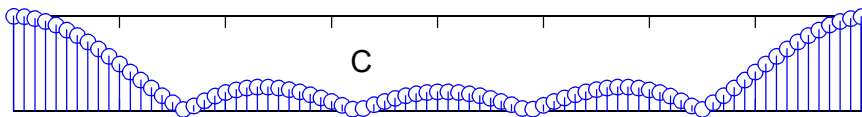
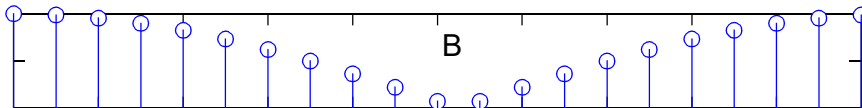
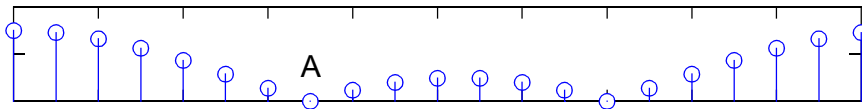
$$\text{But } Y(z) = 10 \quad \Rightarrow \quad \frac{B}{10} = 0.2 \quad \Rightarrow \quad B = 2$$

PROB. Su18-Fin.6.

Shown below are eleven different outcomes that result from executing the MATLAB code:

```
stem(abs(fft(ones(1,L),N)));
```

Match each plot with the corresponding values for the variables N and L by writing a letter (A through K) in each answer box.



- $L = 2, N = 21$ B
- $L = 2, N = 81$ E
- $L = 3, N = 21$ A
- $L = 3, N = 81$ K
- $L = 4, N = 21$ F
- $L = 4, N = 81$ H
- $L = 5, N = 21$ G
- $L = 5, N = 81$ C
- $L = 8, N = 81$ J
- $L = 21, N = 21$ D
- $L = 21, N = 81$ I

PROB. Su18-Fin.7. (The different parts are unrelated.)

(a) There are an infinite number of values for the delay parameter t_0 below such that:

$$\cos(100\pi t) + \cos(100\pi(t - t_0)) + \cos(100\pi(t - 2t_0)) = 0, \quad \text{for all time } t.$$

Name any two, both positive:

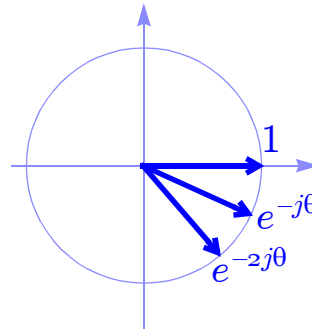
$$t_0 = \boxed{\frac{1}{150}},$$


or

$$t_0 = \boxed{\frac{1}{75}}.$$

Phasor addition rule, where $\theta = 100\pi t_0$:

$$0 = 1 + e^{-j\theta} + e^{-j2\theta}$$



In order for these phasors to add to zero, they must form a "peace sign", with equally spaced angles 

\Rightarrow add to zero when either

$$\theta = \frac{2\pi}{3} + m2\pi \quad \Rightarrow \quad t_0 = \frac{1 + 3m}{150} \in \left\{ \frac{1}{150}, \frac{4}{150}, \frac{7}{150}, \frac{10}{150}, \dots \right\}$$

$$\text{or} \quad \theta = \frac{4\pi}{3} + k2\pi \quad \Rightarrow \quad t_0 = \frac{2 + 3k}{150} \in \left\{ \frac{2}{150}, \frac{5}{150}, \frac{8}{150}, \frac{11}{150}, \dots \right\}$$

(b) Simplify

$$\sum_{k=-\infty}^{\infty} \frac{\sin(0.9\pi k)}{\pi k} \cdot \frac{\sin(0.75\pi(n-k))}{\pi(n-k)} =$$

$$\boxed{\frac{\sin(0.75\pi n)}{\pi n}}$$

a function of n

Recognize as the convolution of

$$h[n] = \frac{\sin(0.9\pi n)}{\pi n} \quad \text{with} \quad x[n] = \frac{\sin(0.75\pi n)}{\pi n}.$$

$$y[n] = x[n] * h[n] \Rightarrow Y(e^{j\hat{\omega}}) = X(e^{j\hat{\omega}})H(e^{j\hat{\omega}}) = X(e^{j\hat{\omega}})$$

(narrow)(wide)

(multiplying a narrow rectangle by a wide rectangle yields a narrow rectangle) $\Rightarrow y[n] = x[n].$

- (c) The signal $x(t) = \cos(88\pi t)\cos(8\pi t) + \cos(240\pi t)$ is periodic with fundamental frequency

$$f_0 = \boxed{8} \text{ Hz.}$$

Multiplying the 44-Hz sinusoid by the 4-Hz sinusoid leads to the sum of two sinusoids, one with frequency 40 Hz and the other with frequency 48 Hz, so overall $x(t)$ has contributions at three frequencies:

$$40 \text{ Hz} = (8)(5)$$

$$48 \text{ Hz} = (8)(6)$$

$$120 \text{ Hz} = (8)(15)$$

\Rightarrow greatest common factor is 8

- (d) If $\{X[0], \dots, X[511]\}$ are the DFT coefficients that result from taking a 512-point DFT of the length-12 signal $x[n] = [1 \ 1 \ 1 \ 2 \ 2 \ 2 \ 3 \ 3 \ 3 \ 4 \ 4 \ 4]$ for $n \in \{0, \dots, 11\}$, then find numerical values for the following two DFT coefficients:

$$X[0] = \boxed{30},$$

$$X[256] = \boxed{-2}.$$

$$X[k] = \sum_n x[n] e^{-jk2\pi n/N}$$

$$\Rightarrow X[0] = \sum_n x[n] = 1 + 1 + 1 + 2 + 2 + 2 + 3 + 3 + 3 + 4 + 4 + 4 = 30$$

$$\Rightarrow X[256] = \sum_n x[n] e^{-j\pi n} = 1 - 1 + 1 - 2 + 2 - 2 + 3 - 3 + 3 - 4 + 4 - 4 = -2$$