

GEORGIA INSTITUTE OF TECHNOLOGY  
SCHOOL OF ELECTRICAL AND COMPUTER ENGINEERING

**ECE 2026 Spring 2025  
Final Exam**

April 25, 2025

NAME: \_\_\_\_\_  
(FIRST) (LAST)

GT username: \_\_\_\_\_  
(e.g., gtxyz123)

Circle your recitation section:

L01 (Daniela)

L05 (Chun-Wei)

L07 (Chun-Wei)

L09 (Daniela)

L02 (Greg)

L06 (Kennedy)

L08 (Kennedy)

L10 (Greg)

**Important Notes:**

- You may tear off the tables from the back of the exam, but otherwise do not unstaple the rest.
- Do not unstaple the test.
- Closed book, except for one two-sided page (8.5" × 11") of hand-written notes.
- Calculators are allowed, but no other electronics (no sphones/watches/readers/tablets/laptops/etc).
- JUSTIFY your reasoning CLEARLY to receive partial credit.
- Express all angles as a fraction of  $\pi$ . For example, write  $0.1\pi$  as opposed to  $18^\circ$  or 0.3142 radians.
- You must write your answer in the space provided on the exam paper itself.  
Only these answers will be graded. Write your answers in the provided answer boxes.
- Only the fronts of the each page will be scanned and graded.

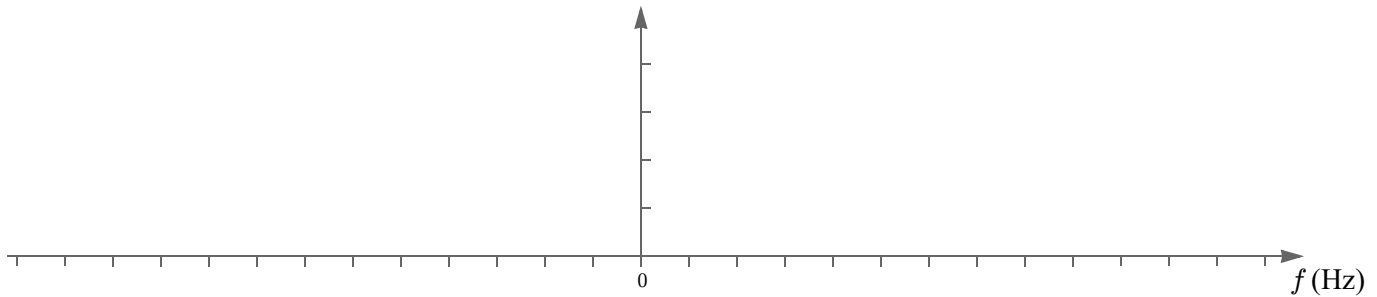
Problem	Value	Score
1	15	
2	16	
3	17	
4	9	
5	16	
6	16	
7	11	
Total		

**PROB. Sp25-F.1.** Consider the signal  $s(t) = 4\cos(16\pi t) + 2\sin(24\pi t)$ .

- (a) The signal  $s(t)$  is periodic with fundamental frequency

Hz.

- (b) In the space below, carefully sketch the two-sided spectrum for  $s(t)$ ; full credit requires that the frequency and complex coefficient for *each line* be clearly *labeled*:

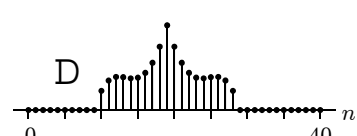
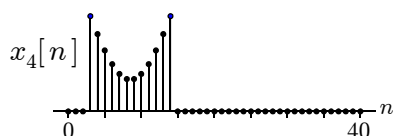
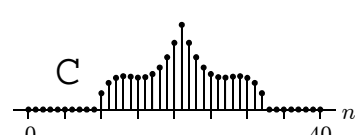
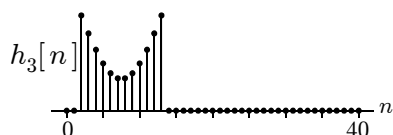
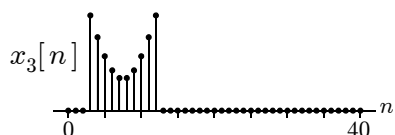
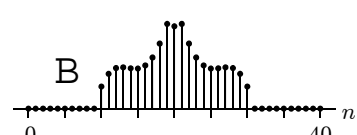
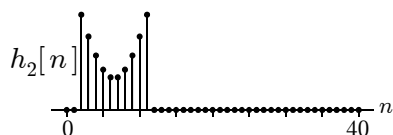
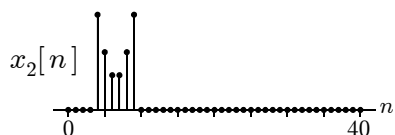
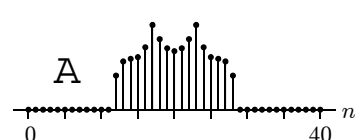
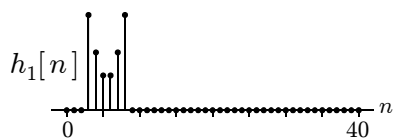


- (c) Construct a new signal according to  $x(t) = 2\cos(4\pi t)s(t)$ .

The Fourier series representation for this new signal is  $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk2\pi f_0 t}$ , where:

$f_0 =$	<input type="text"/>	Hz,	$a_0 =$	<input type="text"/>	,
			$a_1 =$	<input type="text"/>	,
			$a_2 =$	<input type="text"/>	,
			$a_3 =$	<input type="text"/>	,
			$a_4 =$	<input type="text"/>	,
			$a_5 =$	<input type="text"/>	,
			$a_6 =$	<input type="text"/>	,
			$a_7 =$	<input type="text"/>	.

**PROB. Sp25-F.2.** Shown below are the stem plots of four input sequences  $x_1[n]$  through  $x_4[n]$ , along with three impulse responses  $h_1[n]$  through  $h_3[n]$ :



Match each convolution below to one of the nine stem plots shown to the right. Answer by writing a letter from  $\{A, \dots, I\}$  into each answer box. (Some letters used more than once.)

(Hint: Pay close attention to the durations of the signals.)

(a)  $x_1[n] * h_1[n]$

(g)  $x_3[n] * h_2[n]$

(b)  $x_2[n] * h_1[n]$

(h)  $x_4[n] * h_2[n]$

(c)  $x_3[n] * h_1[n]$

(i)  $x_1[n] * h_3[n]$

(d)  $x_4[n] * h_1[n]$

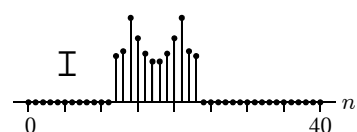
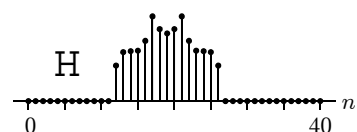
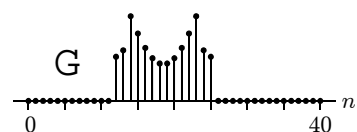
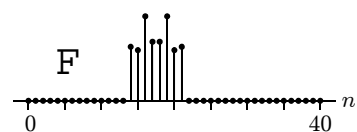
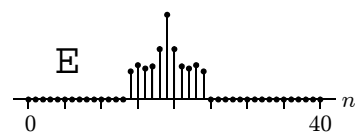
(j)  $x_2[n] * h_3[n]$

(e)  $x_1[n] * h_2[n]$

(k)  $x_3[n] * h_3[n]$

(f)  $x_2[n] * h_2[n]$

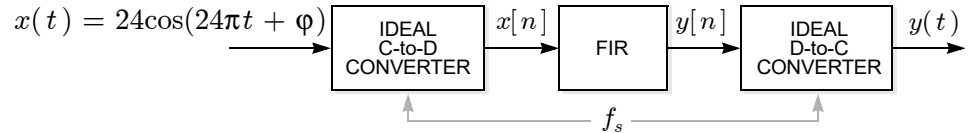
(l)  $x_4[n] * h_3[n]$



**PROB. Sp25-F.3.**

Consider the FIR filter defined by the difference equation:  $y[n] = x[n] + x[n-1] + x[n-2]$ .

Suppose the sinusoid  $x(t) = 24\cos(24\pi t + \phi)$  with unspecified phase  $\phi$  is fed to an ideal sampling/filtering/reconstruction system using the above FIR filter, producing an output  $y(t)$ :



(a) To avoid aliasing we need  $f_s > \boxed{\phantom{000}}$  Hz.

(b) For the case when  $\phi = 0$ , there are many sampling rates for which the D-to-C output  $y(t)$  is zero for all time  $t$ .

Of these, the *largest* is  $f_s = \boxed{\phantom{000}}$  Hz, and the *second-largest* is  $f_s = \boxed{\phantom{000}}$  Hz.

(c) For the case when  $\phi = -\pi/2$ , there are again many sampling rates for which  $y(t)$  is zero for all  $t$ , and the largest of these is the same as in (b), but now the *second-largest* is  $f_s = \boxed{\phantom{000}}$  Hz.  
different from part (b)

**PROB. Sp25-F.4.** Shown below are nine plots of  $\left| \sum_{n=0}^{49} \cos(\hat{\omega}n) e^{-jk2\pi n/50} \right|$  versus  $k \in \{0, \dots, 49\}$ , labeled A through I. (The y-axis scales are not labeled, only the shapes matter.) Match each plot to the corresponding value (in units of radians) of the parameter  $\hat{\omega}$ . Answer by writing a letter (from A through I) into each answer box.

(1)   $\hat{\omega} = 1$

(2)   $\hat{\omega} = 3$

(3)   $\hat{\omega} = 6$

(4)   $\hat{\omega} = 9$

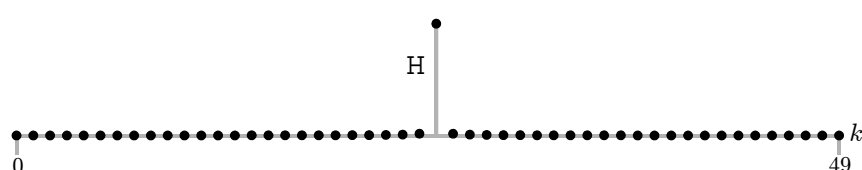
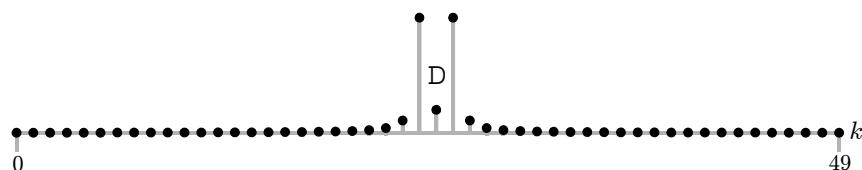
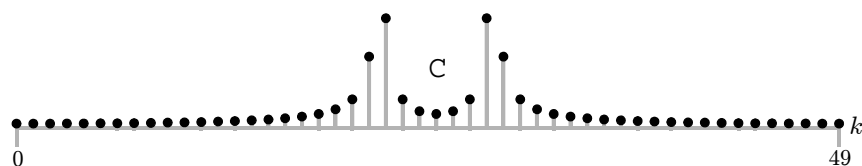
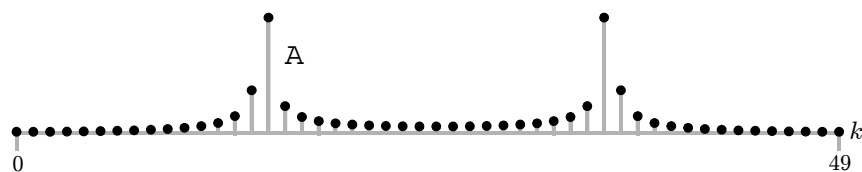
(5)   $\hat{\omega} = 17$

(6)   $\hat{\omega} = 20$

(7)   $\hat{\omega} = 22$

(8)   $\hat{\omega} = 33$

(9)   $\hat{\omega} = 333$



**PROB. Sp25-F.5.** An LTI filter's impulse response  $h[n]$  is defined in terms of  $g[n] = \frac{\cos(\hat{\omega}_0 n) \sin(\hat{\omega}_1 n)}{\pi n}$  according to:

$$h[n] = 5g[n] + g[n - N] + g[n + N].$$

Shown on the right are eight different frequency response plots for this filter, each resulting from a different set of values for the parameters  $\hat{\omega}_0$ ,  $\hat{\omega}_1$ , and  $N$ . Match each plot to one of the eight parameter sets listed below.

(1)   $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 2$

(2)   $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 2$

(3)   $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 2$

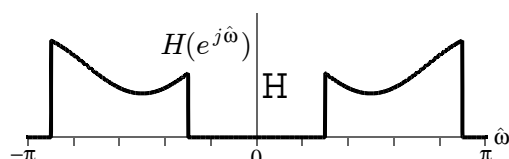
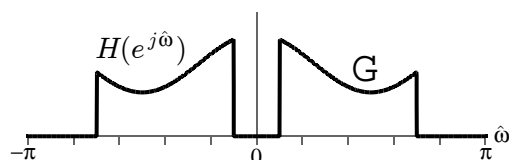
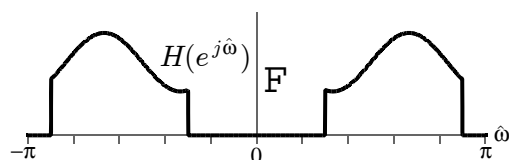
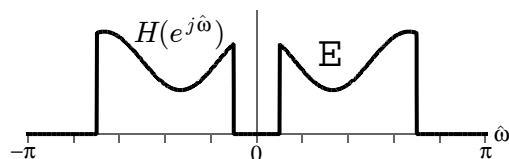
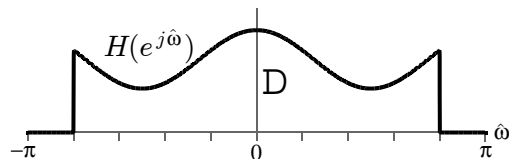
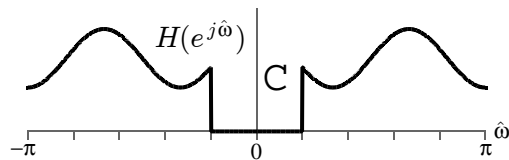
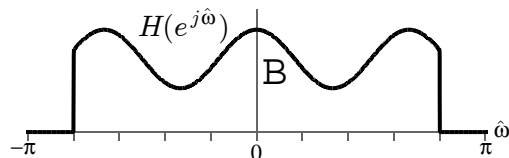
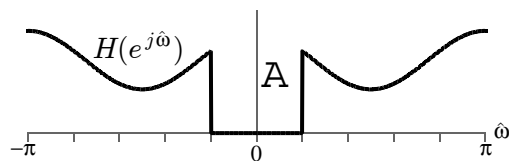
(4)   $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 2$

(5)   $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 3$

(6)   $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 3$

(7)   $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 3$

(8)   $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 3$



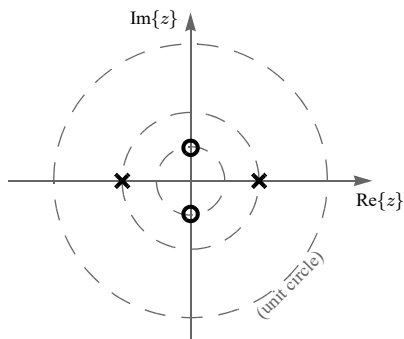
**PROB. Sp25-F.6.** An LTI filter is defined by the following difference equation, with parameters  $a$  and  $b$  that differ in the different parts below:

$$y[n] = x[n] + ay[n-2] + bx[n-2].$$

- (a) If the output is  $y[n] = 0$  (for all  $n$ ) when the filter parameters are  $a = 0.2$  and  $b = 1$  and when the input is  $x[n] = 0.3\cos(\hat{\omega}_0 n + 0.3\pi)$ , the input frequency must be

$$\hat{\omega}_0 = \boxed{\phantom{0.3\pi}}.$$

- (b) Find  $a$  and  $b$  so that the pole-zero plot for the system function  $H(z)$  is as shown below, with the zeros falling on the intersection of the vertical axis and a circle of radius 0.25, and the poles falling on the intersection of the horizontal axis and a circle of radius 0.5:



$$a = \boxed{\phantom{0.2}},$$

$$b = \boxed{\phantom{0.2}}.$$

- (c) Find  $a$  and  $b$  so that the output in response to  $x[n] = 8 + 10\cos(0.5\pi(n-2))$  is

$$y[n] = 40 + 40\cos(0.5\pi(n-2)):$$

$$a = \boxed{\phantom{0.2}},$$

$$b = \boxed{\phantom{0.2}}.$$

**PROB. Sp25-F.7.**

Shown on the left are the pole-zero plots for eleven LTI systems, labeled A through K. Shown on the right are the corresponding magnitude responses  $|H(e^{j\omega})|$ , but in a scrambled order. Match the pole-zero plot to its corresponding magnitude response by writing a letter (A through K) in each answer box.

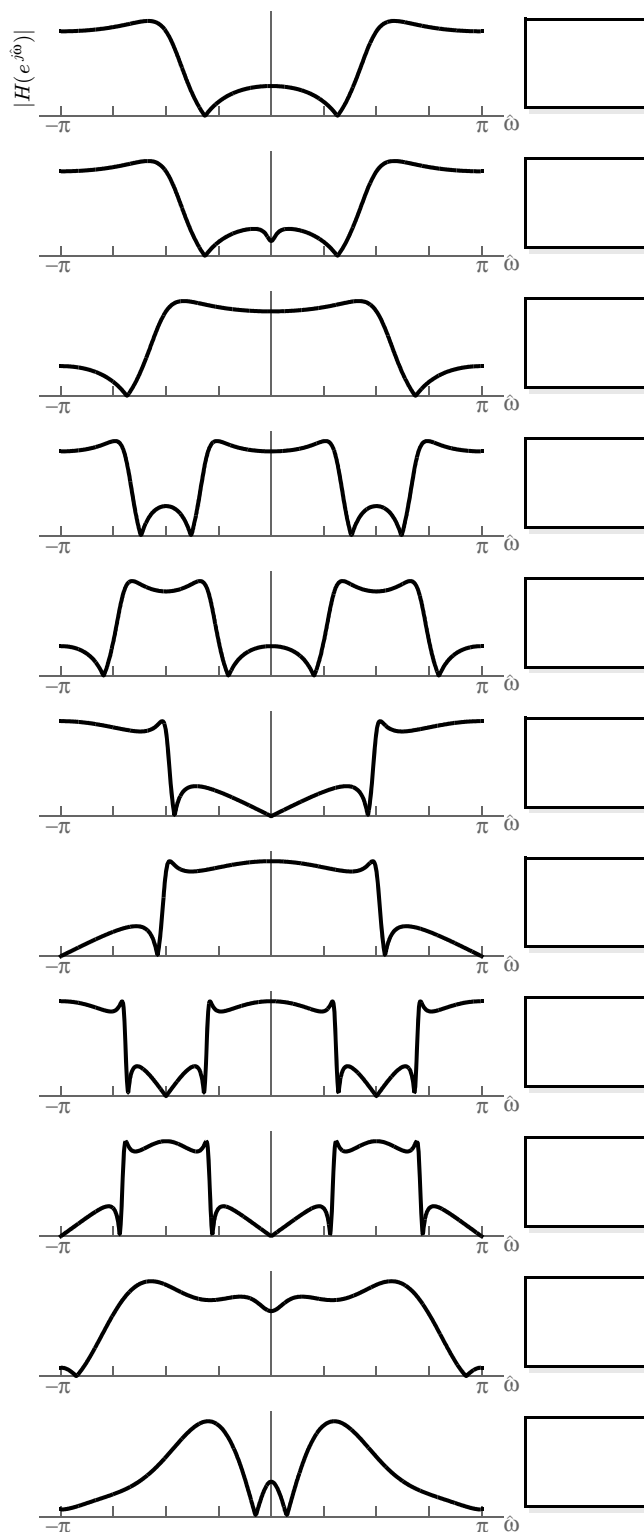
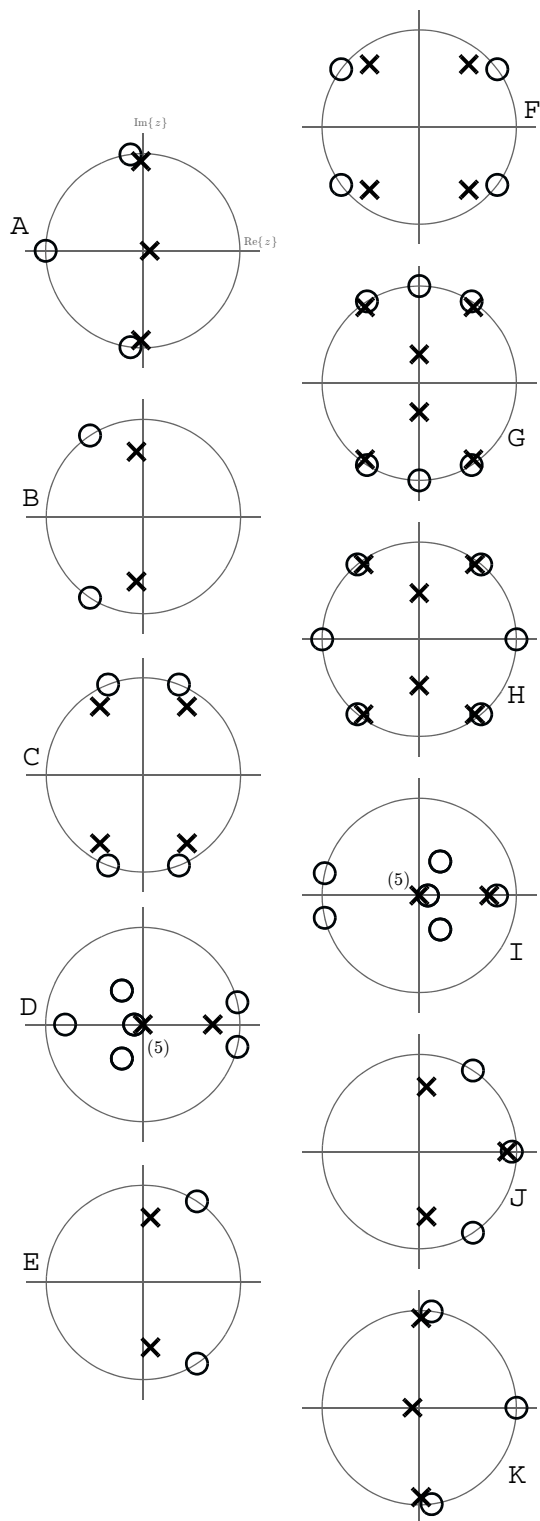




Table of DTFT Pairs	
<i>Time-Domain: <math>x[n]</math></i>	<i>Frequency-Domain: <math>X(e^{j\hat{\omega}})</math></i>
$\delta[n]$	1
$\delta[n - n_0]$	$e^{-j\hat{\omega}n_0}$
$r_L[n] = u[n] - u[n - L]$	$\frac{\sin(\frac{1}{2}L\hat{\omega})}{\sin(\frac{1}{2}\hat{\omega})} e^{-j\hat{\omega}(L-1)/2}$
$r_L[n]e^{j\hat{\omega}_0n}$	$\frac{\sin(\frac{1}{2}L(\hat{\omega} - \hat{\omega}_0))}{\sin(\frac{1}{2}(\hat{\omega} - \hat{\omega}_0))} e^{-j(\hat{\omega} - \hat{\omega}_0)(L-1)/2}$
$\frac{\sin(\hat{\omega}_b n)}{\pi n}$	$u(\hat{\omega} + \hat{\omega}_b) - u(\hat{\omega} - \hat{\omega}_b) = \begin{cases} 1 &  \hat{\omega}  \leq \hat{\omega}_b \\ 0 & \hat{\omega}_b <  \hat{\omega}  \leq \pi \end{cases}$
$a^n u[n] \quad ( a  < 1)$	$\frac{1}{1 - ae^{-j\hat{\omega}}}$

Table of DTFT Properties		
<i>Property Name</i>	<i>Time-Domain: <math>x[n]</math></i>	<i>Frequency-Domain: <math>X(e^{j\hat{\omega}})</math></i>
Periodic in $\hat{\omega}$		$X(e^{j(\hat{\omega}+2\pi)}) = X(e^{j\hat{\omega}})$
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(e^{j\hat{\omega}}) + bX_2(e^{j\hat{\omega}})$
Conjugate Symmetry	$x[n]$ is real	$X(e^{-j\hat{\omega}}) = X^*(e^{j\hat{\omega}})$
Conjugation	$x^*[n]$	$X^*(e^{-j\hat{\omega}})$
Time-Reversal	$x[-n]$	$X(e^{-j\hat{\omega}})$
Delay ( $n_d$ =integer)	$x[n - n_d]$	$e^{-j\hat{\omega}n_d} X(e^{j\hat{\omega}})$
Frequency Shift	$x[n]e^{j\hat{\omega}_0n}$	$X(e^{j(\hat{\omega}-\hat{\omega}_0)})$
Modulation	$x[n] \cos(\hat{\omega}_0n)$	$\frac{1}{2}X(e^{j(\hat{\omega}-\hat{\omega}_0)}) + \frac{1}{2}X(e^{j(\hat{\omega}+\hat{\omega}_0)})$
Convolution	$x[n] * h[n]$	$X(e^{j\hat{\omega}})H(e^{j\hat{\omega}})$
Autocorrelation	$x[-n] * x[n]$	$ X(e^{j\hat{\omega}}) ^2$
Parseval's Theorem	$\sum_{n=-\infty}^{\infty}  x[n] ^2$	$\frac{1}{2\pi} \int_{-\pi}^{\pi}  X(e^{j\hat{\omega}}) ^2 d\hat{\omega}$

Table of Pairs for $N$ -point DFT	
<i>Time-Domain:</i> $x[n], \quad n = 0, 1, 2, \dots, N - 1$	<i>Frequency-Domain:</i> $X[k], \quad k = 0, 1, 2, \dots, N - 1$
If $x[n]$ is finite length, i.e., $x[n] \neq 0$ only when $n \in [0, N - 1]$ and the DTFT of $x[n]$ is $X(e^{j\hat{\omega}})$	$X[k] = X(e^{j\hat{\omega}}) \Big _{\hat{\omega}=2\pi k/N}$ (frequency sampling the DTFT)
$\delta[n]$	1
1	$N\delta[k]$
$\delta[n - n_0]$	$e^{-j(2\pi k/N)n_0}$
$e^{j(2\pi n/N)k_0}$	$N\delta[k - k_0]$ , when $k_0 \in [0, N - 1]$
$r_L[n] = u[n] - u[n - L]$ , when $L \leq N$	$\frac{\sin(\frac{1}{2}L(2\pi k/N))}{\sin(\frac{1}{2}(2\pi k/N))} e^{-j(2\pi k/N)(L-1)/2}$
$r_L[n]e^{j(2\pi k_0/N)n}$ , when $L \leq N$	$\frac{\sin(\frac{1}{2}L(2\pi(k - k_0)/N))}{\sin(\frac{1}{2}(2\pi(k - k_0)/N))} e^{-j(2\pi(k - k_0)/N)(L-1)/2}$
$\frac{\sin(\frac{1}{2}L(2\pi n/N))}{\sin(\frac{1}{2}(2\pi n/N))} e^{j(2\pi n/N)(L-1)/2}$	$N(u[k] - u[k - L])$ , when $L \leq N$

Table of DFT Properties		
<i>Property Name</i>	<i>Time-Domain:</i> $x[n]$	<i>Frequency-Domain:</i> $X[k]$
Periodic	$x[n] = x[n + N]$	$X[k] = X[k + N]$
Linearity	$ax_1[n] + bx_2[n]$	$aX_1[k] + bX_2[k]$
Conjugate Symmetry	$x[n]$ is real	$X[N - k] = X^*[k]$
Conjugation	$x^*[n]$	$X^*[N - k]$
Time-Reversal	$x[N - n]$	$X[N - k]$
Delay (PERIODIC)	$x[n - n_d]$	$e^{-j(2\pi k/N)n_d} X[k]$
Frequency Shift	$x[n]e^{j(2\pi k_0/N)n}$	$X[k - k_0]$
Modulation	$x[n] \cos((2\pi k_0/N)n)$	$\frac{1}{2}X[k - k_0] + \frac{1}{2}X[k + k_0]$
Convolution (PERIODIC)	$x[n] * h[n] = \sum_{m=0}^{N-1} h[m]x[n - m]$	$X[k]H[k]$
Parseval's Theorem	$\sum_{n=0}^{N-1}  x[n] ^2 = \frac{1}{N} \sum_{k=0}^{N-1}  X[k] ^2$	

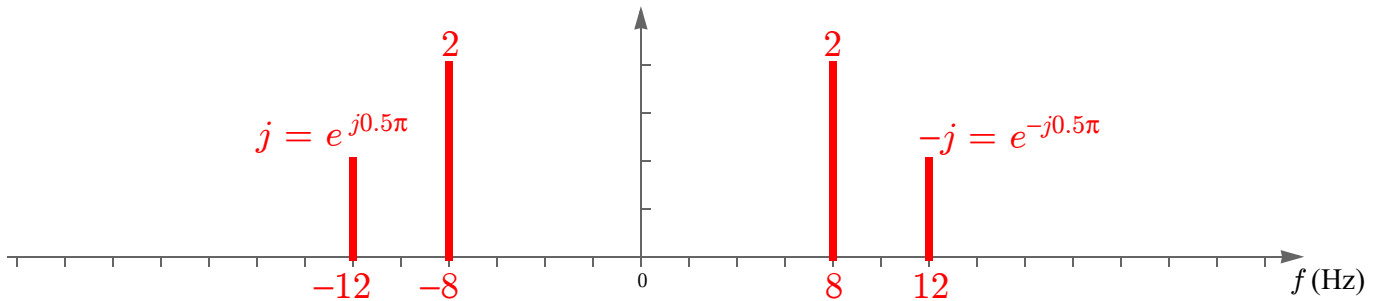
Table of $z$ -Transform Pairs		
Signal Name	Time-Domain: $x[n]$	$z$ -Domain: $X(z)$
Impulse	$\delta[n]$	1
Shifted impulse	$\delta[n - n_0]$	$z^{-n_0}$
Right-sided exponential	$a^n u[n]$	$\frac{1}{1 - az^{-1}}, \quad  a  < 1$
Decaying cosine	$r^n \cos(\hat{\omega}_0 n) u[n]$	$\frac{1 - r \cos(\hat{\omega}_0) z^{-1}}{1 - 2r \cos(\hat{\omega}_0) z^{-1} + r^2 z^{-2}}$
Decaying sinusoid	$Ar^n \cos(\hat{\omega}_0 n + \varphi) u[n]$	$A \frac{\cos(\varphi) - r \cos(\hat{\omega}_0 - \varphi) z^{-1}}{1 - 2r \cos(\hat{\omega}_0) z^{-1} + r^2 z^{-2}}$

Table of $z$ -Transform Properties		
Property Name	Time-Domain $x[n]$	$z$ -Domain $X(z)$
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$
Delay ( $d$ =integer)	$x[n - d]$	$z^{-d} X(z)$
Convolution	$x[n] * h[n]$	$X(z)H(z)$

Problem	Value	Score
1	15	
2	16	
3	17	
4	9	
5	16	
6	16	
7	11	
Total		

**PROB. Sp25-F.1.** Consider the signal  $s(t) = 4\cos(16\pi t) + 2\sin(24\pi t)$ .

- (a) The signal  $s(t)$  is periodic with fundamental frequency  $f_0 = \gcd(8, 12) =$  4 Hz.
- (b) In the space below, carefully sketch the two-sided spectrum for  $s(t)$ ;  
full credit requires that the frequency and complex coefficient for *each line* be clearly labeled:



- (c) Construct a new signal according to  $x(t) = 2\cos(4\pi t)s(t)$ .

The Fourier series representation for this new signal is  $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk2\pi f_0 t}$ , where:

$$f_0 =$$
 2  $\text{Hz}, \quad a_0 =$  0  $,$

$$a_1 =$$
 0  $,$

$$a_2 =$$
 0  $,$

$$a_3 =$$
 2  $,$

$$a_4 =$$
 0  $,$

$$a_5 =$$
  $2 - j$   $,$

$$a_6 =$$
 0  $,$

$$a_7 =$$
  $-j$   $.$

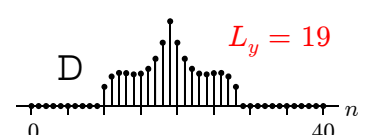
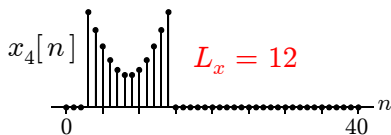
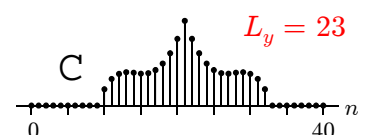
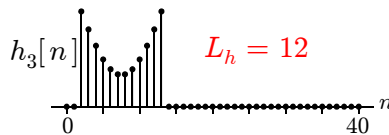
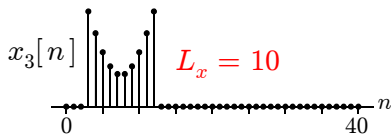
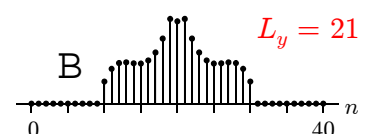
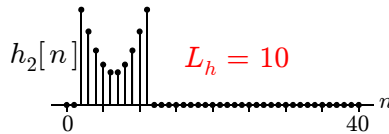
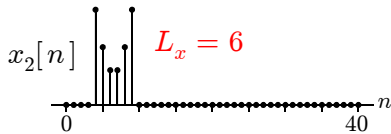
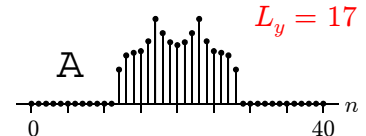
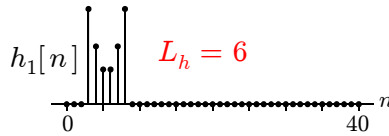
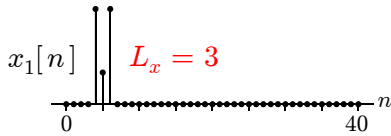
$$\begin{aligned} x(t) &= 8\cos(4\pi t)\cos(16\pi t) + 4\cos(4\pi t)\sin(24\pi t) \\ &= 4\cos(20\pi t) + 4\cos(12\pi t) + 2\sin(28\pi t) + 2\sin(20\pi t) \\ &= A\cos(20\pi t + \varphi) + 4\cos(12\pi t) + 2\sin(28\pi t) \end{aligned}$$

where phasor addition  $\Rightarrow Ae^{j\varphi} = 4 - 2j$

$$f_0 = \gcd(6, 10, 14) = 2$$

Length after convolution is  $L_y = L_x + L_h - 1$

**PROB. Sp25-F.2.** Shown below are the stem plots of four input sequences  $x_1[n]$  through  $x_4[n]$ , along with three impulse responses  $h_1[n]$  through  $h_3[n]$ :



Match each convolution below to one of the nine stem plots shown to the right. Answer by writing a letter from {A, ... I} into each answer box. (Some letters used more than once.)

(Hint: Pay close attention to durations of the signals.)

**F** (a)  $x_1[n] * h_1[n]$

**D** (g)  $x_3[n] * h_2[n]$

**E** (b)  $x_2[n] * h_1[n]$

**B** (h)  $x_4[n] * h_2[n]$

**H** (c)  $x_3[n] * h_1[n]$

**G** (i)  $x_1[n] * h_3[n]$

**A** (d)  $x_4[n] * h_1[n]$

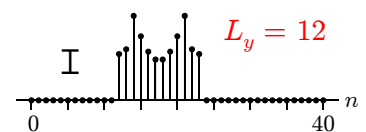
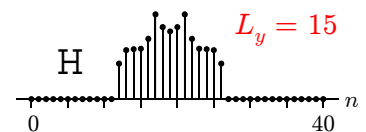
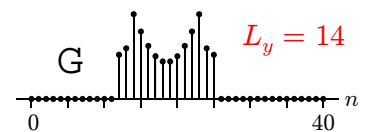
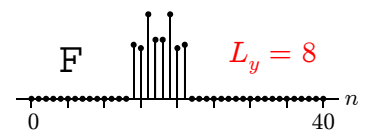
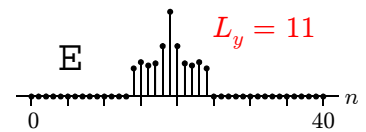
**A** (j)  $x_2[n] * h_3[n]$

**I** (e)  $x_1[n] * h_2[n]$

**B** (k)  $x_3[n] * h_3[n]$

**H** (f)  $x_2[n] * h_2[n]$

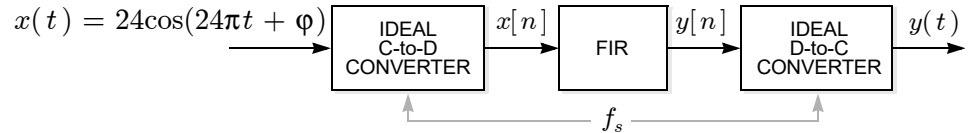
**C** (l)  $x_4[n] * h_3[n]$



**PROB. Sp25-F.3.**

Consider the FIR filter defined by the difference equation:  $y[n] = x[n] + x[n-1] + x[n-2]$ .

Suppose the sinusoid  $x(t) = 24\cos(24\pi t + \varphi)$  with unspecified phase  $\varphi$  is fed to an ideal sampling/filtering/reconstruction system using the above FIR filter, producing an output  $y(t)$ :



(a) To avoid aliasing we need  $f_s > \boxed{24}$  Hz.

(b) For the case when  $\varphi = 0$ , there are many sampling rates for which the D-to-C output  $y(t)$  is zero for all time  $t$ .

Of these, the *largest* is  $f_s = \boxed{36}$  Hz, and the *second-largest* is  $f_s = \boxed{18}$  Hz.

The  $\{b_k\} = \{1 \ 1 \ 1\}$  filter nulls  $\hat{\omega}_0 = \frac{2\pi}{3}$

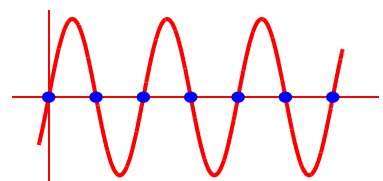
$\Rightarrow$  Smallest digital frequency nulled is  $\frac{24\pi}{f_s} = \frac{2\pi}{3} \Rightarrow f_s = 36$  Hz

$\Rightarrow$  second-smallest is  $\frac{24\pi}{f_s} = \left| \frac{2\pi}{3} - 2\pi \right| = \frac{4\pi}{3} \Rightarrow f_s = 18$  Hz

(c) For the case when  $\varphi = -\pi/2$ , there are again many sampling rates for which  $y(t)$  is zero for all  $t$ , and the largest of these is the same as in (b), but now the *second-largest* is  $f_s = \boxed{24}$  Hz.  
different from part (b)

In this case the input is  $24\sin(24\pi t)$ , a pure sine, which can be sampled at its zero crossings to get a zero signal even before the FIR filter:

when  $f_s = 24$  Hz:

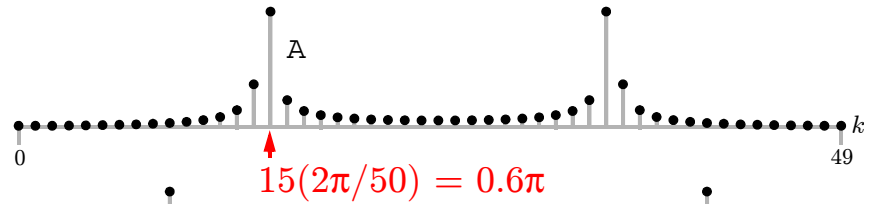


Reduce digital frequencies to  $\in(-\pi, \pi)$  and express in terms of  $\pi$ :

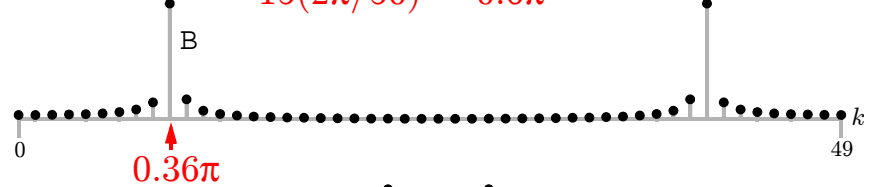
PROB. Sp25-F.4.

Shown below are nine plots of  $|\sum_{n=0}^{49} \cos(\hat{\omega}n) e^{-jk2\pi n/50}|$  versus  $k \in \{0, \dots, 49\}$ , labeled A through I. (The y-axis scales are not labeled, only the shapes matter.) Match each plot to the corresponding value (in units of radians) of the parameter  $\hat{\omega}$ . Answer by writing a letter (from A through I) into each answer box.

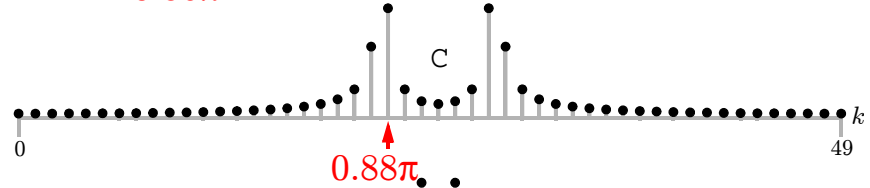
(1) E  $\hat{\omega} = 1$   
 $= 0.32\pi$



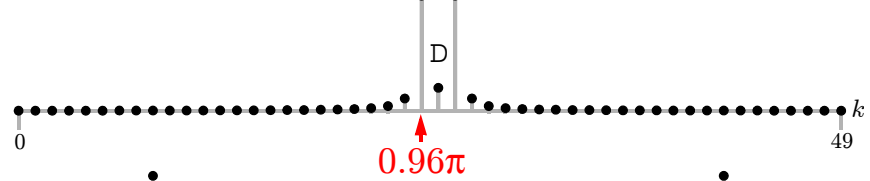
(2) D  $\hat{\omega} = 3$   
 $= 0.96\pi$



(3) F  $\hat{\omega} = 6$   
 $= -0.1\pi$



(4) C  $\hat{\omega} = 9$   
 $= 0.86\pi$



(5) A  $\hat{\omega} = 17$   
 $= -0.59\pi$



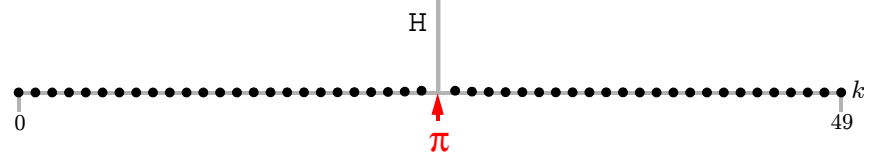
(6) B  $\hat{\omega} = 20$   
 $= 0.37\pi$



(7) H  $\hat{\omega} = 22$   
 $= -0.997\pi$



(8) I  $\hat{\omega} = 33$   
 $= 0.5\pi$



(9) G  $\hat{\omega} = 333$   
 $= -0.003\pi$





**PROB. Sp25-F.5.** An LTI filter's impulse response  $h[n]$  is defined in terms of  $g[n] = \frac{\cos(\hat{\omega}_0 n) \sin(\hat{\omega}_1 n)}{\pi n}$  according to:

$$h[n] = 5g[n] + g[n - N] + g[n + N].$$

Shown on the right are eight different frequency response plots for this filter, each resulting from a different set of values for the parameters  $\hat{\omega}_0$ ,  $\hat{\omega}_1$ , and  $N$ . Match each plot to one of the eight parameter sets listed below.

(1) G  $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 2$

(2) D  $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 2$

(3) H  $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 2$

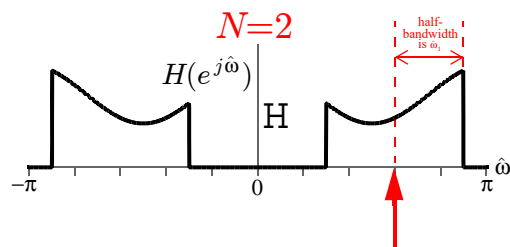
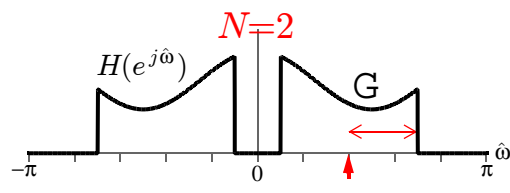
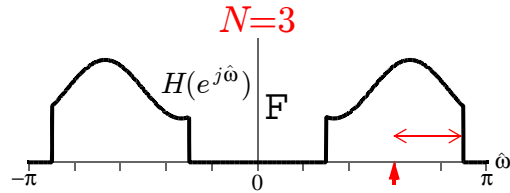
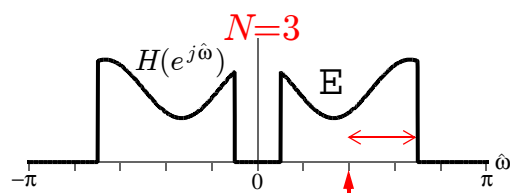
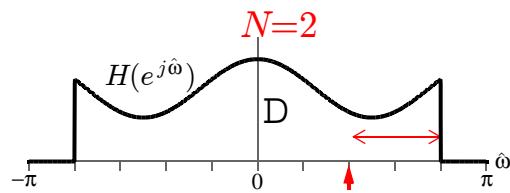
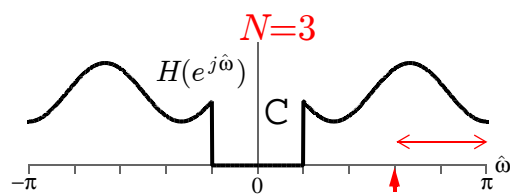
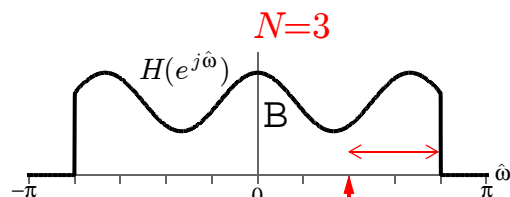
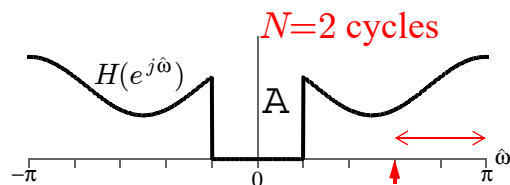
(4) A  $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 2$

(5) E  $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 3$

(6) B  $\hat{\omega}_0 = 0.4\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 3$

(7) F  $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.3\pi$   
 $N = 3$

(8) C  $\hat{\omega}_0 = 0.6\pi$   
 $\hat{\omega}_1 = 0.4\pi$   
 $N = 3$



center of bandpass region is  $\hat{\omega}_0$

**PROB. Sp25-F.6.** An LTI filter is defined by the following difference equation, with parameters  $a$  and  $b$  that differ in the different parts below:

$$y[n] = x[n] + ay[n-2] + bx[n-2].$$

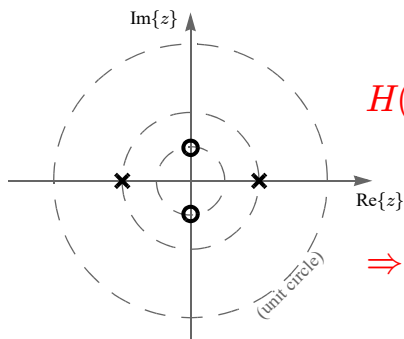
- (a) If the output is  $y[n] = 0$  (for all  $n$ ) when the filter parameters are  $a = 0.2$  and  $b = 1$  and when the input is  $x[n] = 0.3\cos(\hat{\omega}_0 n + 0.3\pi)$ , the input frequency must be

The system function is  $H(z) = \frac{1 + z^{-2}}{1 - az^{-2}} = \frac{z^2 + 1}{z^2 - a}$

$$\hat{\omega}_0 = 0.5\pi$$

$\Rightarrow$  zeros at  $\pm j = e^{\pm j0.5\pi}$ , on the unit circle  $\Rightarrow$  nulls corresponding sinusoid

- (b) Find  $a$  and  $b$  so that the pole-zero plot for the system function  $H(z)$  is as shown below, with the zeros falling on the intersection of the vertical axis and a circle of radius 0.25, and the poles falling on the intersection of the horizontal axis and a circle of radius 0.5:



$$H(z) = \frac{1 + bz^{-2}}{1 - az^{-2}} = \frac{z^2 + b}{z^2 - a}$$

$$\Rightarrow \text{zeros at } \pm j\sqrt{b} \Rightarrow b = \frac{1}{16}$$

$$\text{poles at } \pm \sqrt{a} \Rightarrow a = \frac{1}{4}$$

$$a = \frac{1}{4}, \quad b = \frac{1}{16}$$

- (c) Find  $a$  and  $b$  so that the output in response to  $x[n] = 8 + 10\cos(0.5\pi(n-2))$  is  $y[n] = 40 + 40\cos(0.5\pi(n-2))$ :

$$a = 7, \quad b = -31$$

gain at  $\hat{\omega} = 0$  is  $H(0) = \frac{1+b}{1-a}$

gain at  $\hat{\omega} = 0.5\pi$  is  $H(j) = \frac{1-b}{1+a}$

Set first to 5, second to 4, solve system of equations

$$\left. \begin{aligned} \frac{1+b}{1-a} &= 5 \\ \frac{1-b}{1+a} &= 4 \end{aligned} \right\} \Rightarrow \begin{aligned} a &= 7 \\ b &= -31 \end{aligned}$$

**PROB. Sp25-F.7.**

Shown on the left are the pole-zero plots for eleven LTI systems, labeled A through K. Shown on the right are the corresponding magnitude responses  $|H(e^{j\omega})|$ , but in a scrambled order. Match the pole-zero plot to its corresponding magnitude response by writing a letter (A through K) in each answer box.

