

PROBLEM fall-04-F.1:

In each of the following cases, *simplify the expression as much as possible.*

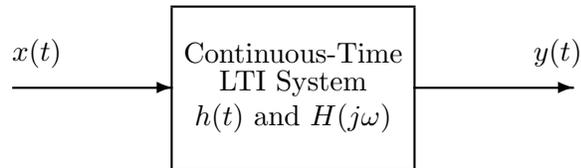
(a) $\cos(3\pi/4t - \pi/2)\delta(t - 3) =$

(b) $[(t + 1)u(t + 1)] * \delta(t - 2) =$

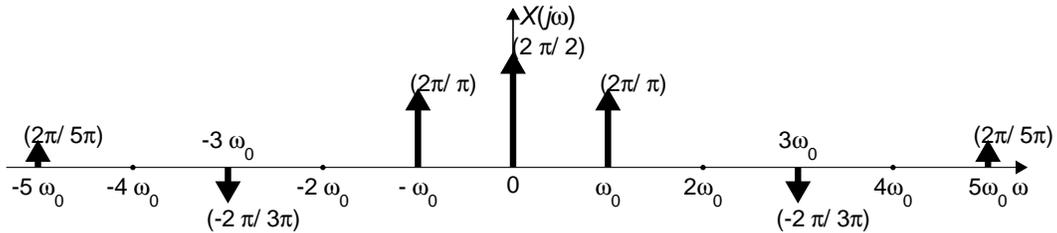
(c) $\int_0^2 e^{-10\tau}\delta(\tau - 3)d\tau =$

(d) $x[n] = 5\cos(0.3\pi n + \pi/2) + 5\sqrt{2}\cos(0.3\pi n - \pi/4) =$

PROBLEM fall-04-F.2:



The periodic input to the above LTI system has the Fourier transform $X(j\omega)$ drawn below:



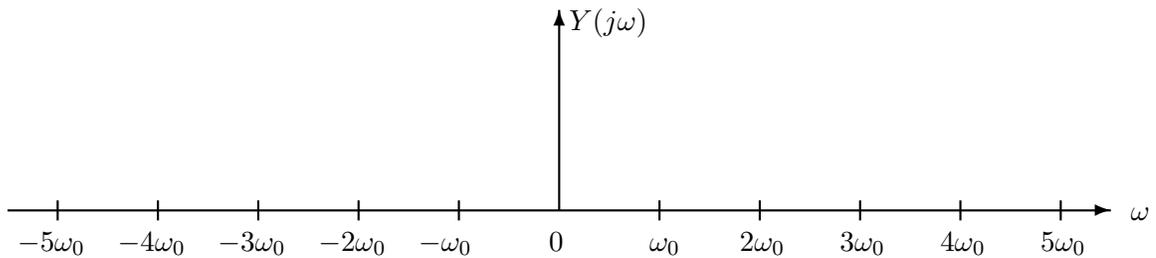
where the dark arrows denote impulses.

- (a) If the frequency response of the filter is given by

$$H(j\omega) = \begin{cases} e^{-2j\omega} & 5\omega_0/2 < |\omega| < 7\omega_0/2 \\ 0 & \text{otherwise} \end{cases}$$

determine $y(t)$. Your answer should be written as a real time function, i.e., there should be no j 's in your answer.

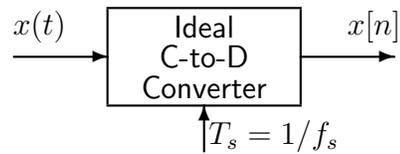
- (b) If $y(t) = x(t - 1)$ sketch $Y(j\omega)$, the spectrum of $y(t)$, on the axes below.



PROBLEM fall-04-F.3:

The individual parts of this problem are independent.

- (a) If the output from an ideal C/D converter is $x[n] = 1000 \cos(0.25\pi n)$, and the sampling rate is 8000 samples/sec, then determine two possible positive values of the input frequency of $x(t)$ that are less than 8000Hz.:



ANS 1: =

ANS 2: =

- (b) Suppose that a student writes the following MATLAB code to generate a sine wave:

```
nn = 0:44100;  
xx = (3/pi) * cos(pi*1.25*nn + pi/3);  
soundsc(xx,fsamp)
```

Although the sinusoid was not written to have a frequency of 2100 Hz, it is possible to play out the vector `xx` so that it sounds like a 2100 Hz tone. Determine the value of `fsamp` that should be used to play the vector `xx` as a 2100 Hz tone. Write your answer as an integer.

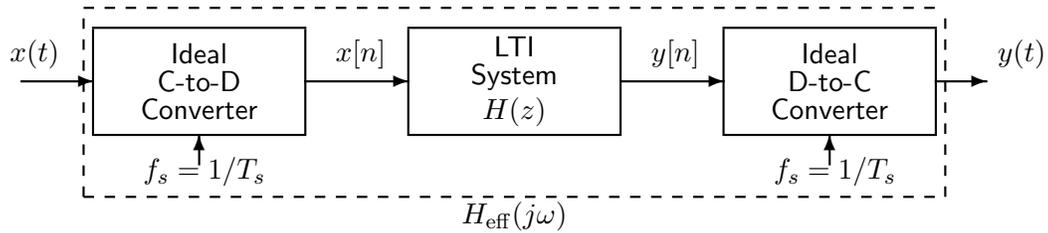
`fsamp` = Hz

- (c) Determine the Nyquist rate for sampling the signal $x(t)$ defined by:
 $x(t) = \Re\{e^{j4000\pi t} + e^{-j3000\pi t}\}.$

ANS = samples/sec.

PROBLEM fall-04-F.4:

Consider the following system for discrete-time filtering of a continuous-time signal:

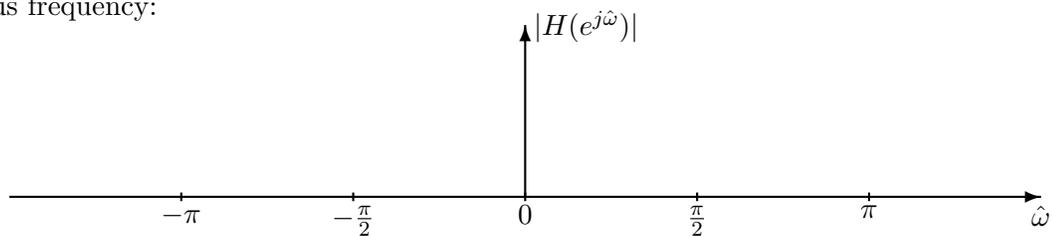


Assume that the discrete-time system is implemented using the MATLAB command:

```
yy=firfilt([0,0,1,0,1],xx)
```

where **xx** is an array of samples of $x[n]$ and **yy** holds samples of $y[n]$.

- (a) Determine the frequency response of the discrete-time filter and plot its magnitude response versus frequency:



- (b) Assume that the input signal $x(t)$ is a sum of cosines:

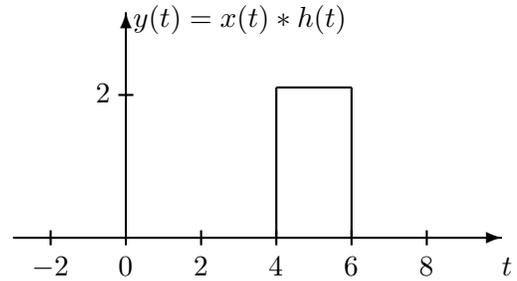
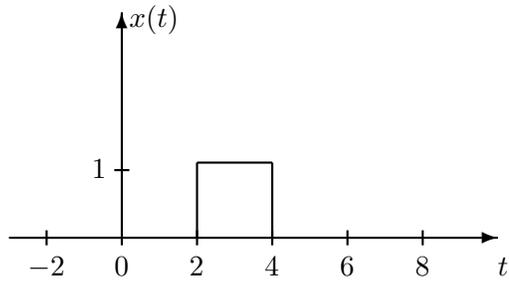
$$x(t) = 3 \cos(100\pi t - \pi/4) + 2 \cos(400\pi t + \pi/3)$$

For this input signal, determine the output signal $y(t)$ when the sampling rate is $f_s = \mathbf{300}$ **samples/sec**. Your answer should be expressed as a sum of cosines.

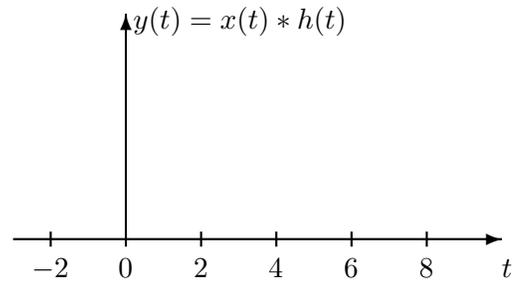
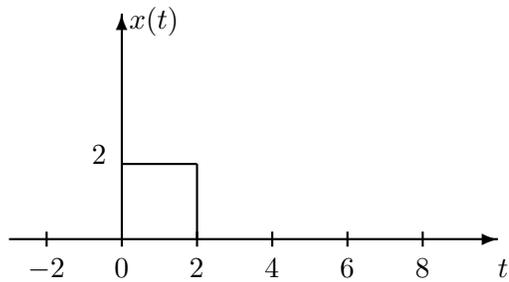
PROBLEM fall-04-F.5:

The parts of this problem are completely independent.

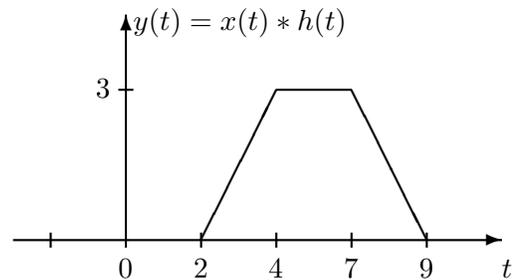
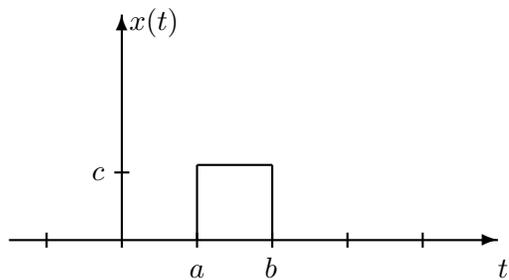
(a) Given that $y(t) = x(t) * h(t)$, find $h(t)$. $h(t) =$



(b) If $h(t) = u(t)$, plot $y(t) = x(t) * h(t)$ on the graph on the right. *Be sure to label the $y(t)$ axis.*



(c) If $h(t) = u(t - 1) - u(t - 3)$ and $y(t) = x(t) * h(t)$, determine the values of a , b , and c in the graph of $x(t)$ on the left, if $y(t)$ is given by the graph on the right.



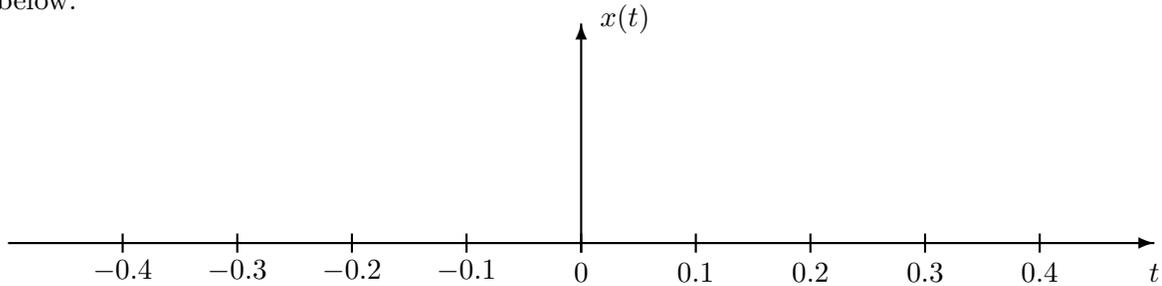
$a =$

$b =$

$c =$

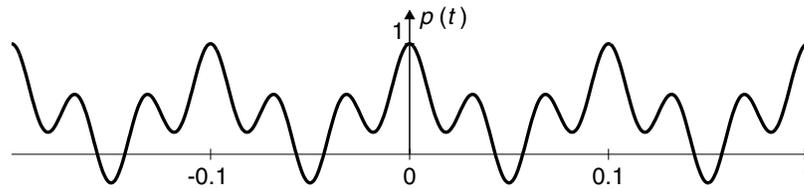
PROBLEM fall-04-F.6:

- (a) Consider the signal $x(t) = \frac{\sin(10\pi t)}{4\pi t}$. Make a carefully labeled sketch of $x(t)$ in the space below.



- (b) Determine the Fourier transform of $y(t) = x(2t - 0.2)$, using $x(t)$ from part (a).

- (c) Now consider the periodic signal $p(t)$ plotted below:

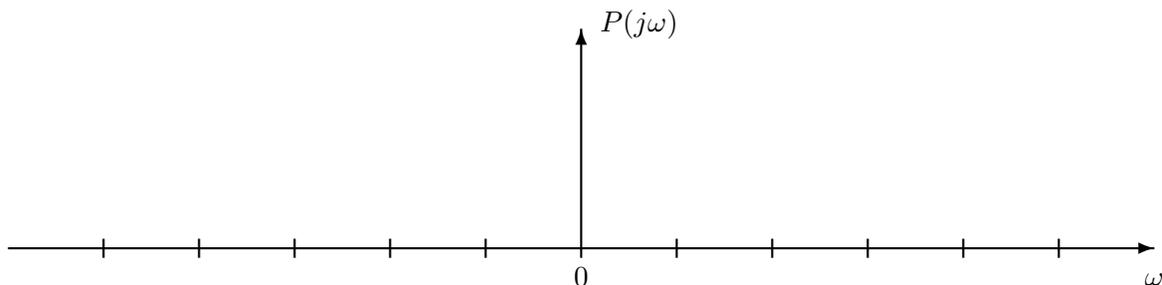


The Fourier series for this input can be simplified to the following form:

$$p(t) = \frac{1}{2} + \frac{2}{\pi} \cos(\omega_0 t) + \frac{2}{\pi} \cos(3\omega_0 t)$$

$\omega_0 =$ _____ rad/sec

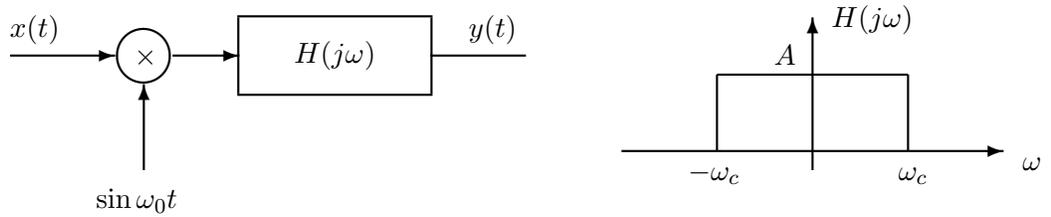
First determine the value of ω_0 and put your result in the box. Then, **either** write an equation for $P(j\omega)$, the Fourier transform of $p(t)$, in the space below, **or** plot it on the axes below. **You must label your plot carefully to receive full credit.**



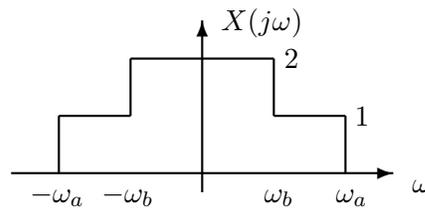
PROBLEM fall-04-F.7:

The two parts of this problem are independent.

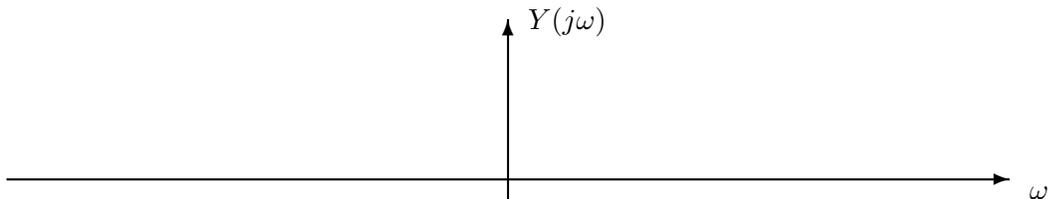
- (a) The system below is proposed as an alternative speech scrambler to the one in lab. Notice that the carrier signal is a sine instead of a cosine.



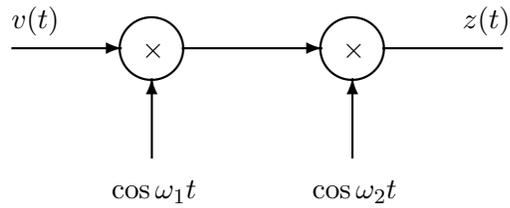
Assume that $x(t)$ has the spectrum, $X(j\omega)$ shown below



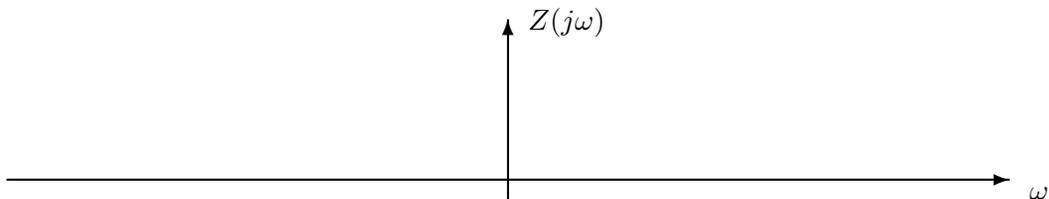
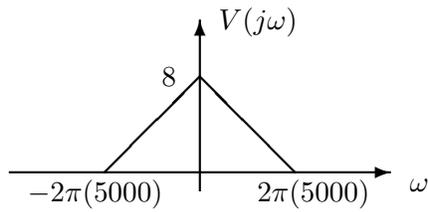
Sketch the spectrum, $Y(j\omega)$ of the output of the scrambler on the axes below if $\omega_a/(2\pi) = 5$ kHz, $\omega_b/(2\pi) = 2$ kHz, $\omega_c/(2\pi) = 5$ kHz, and $\omega_0/(2\pi) = 5$ kHz. Be sure to LABEL YOUR PLOT.



- (b) Signals are often repeatedly moved from one portion of the spectrum to another by repeated mixing. This process is called **heterodyning**. A simple example is the cascade of two mixers shown below.



Let $f_1 = \omega_1/(2\pi) = 30$ kHz and $f_2 = \omega_2/(2\pi) = 20$ kHz. Sketch the spectrum $Z(j\omega)$ assuming that $V(j\omega)$ has the shape shown in the figure below.



PROBLEM fall-04-F.8:

A discrete-time system is defined by the following system function:

$$H(z) = H(z) = \frac{0.64 + z^{-2}}{1 - 0.64z^{-2}}.$$

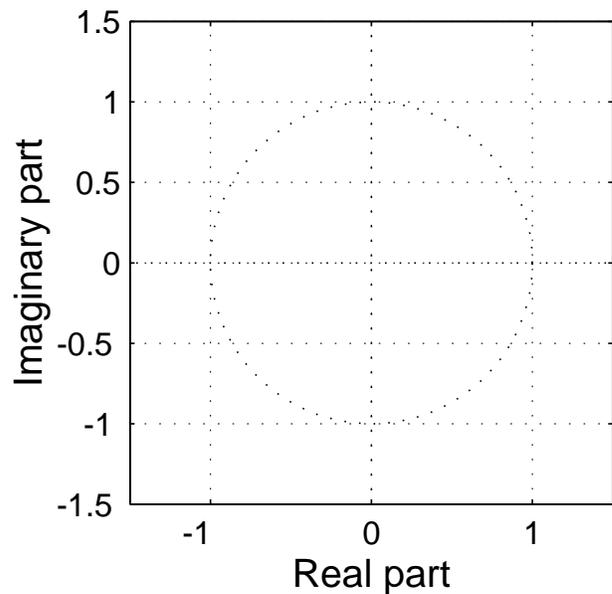
- (a) Write down the difference equation that is satisfied by the input $x[n]$ and output $y[n]$ of the system.

- (b) Fill in numbers for the vectors **bb** and **aa** in the following MATLAB computation of the frequency response of the system:

```
bb=[          ]; aa=[          ];  
yy=filter(bb,aa,xx)
```

where **xx** is the input signal to be filtered.

- (c) Determine *all* the poles and zeros of $H(z)$ and plot them in the z -plane.



- (d) Make a sketch of the magnitude of the frequency response of the system over the range $-\pi < \hat{\omega} \leq \pi$. Indicate where the peaks and valleys are located, and also determine the height of the peaks and the valleys.

PROBLEM fall-04-F.1:

In each of the following cases, *simplify the expression as much as possible.*

$$(a) \cos(3\pi/4t - \pi/2)\delta(t-3) = \boxed{\frac{\sqrt{2}}{2} \delta(t-3)}$$

$$\cos\left(\frac{\pi}{4} - \frac{\pi}{2}\right) \delta(t-3) = \frac{\sqrt{2}}{2} \delta(t-3)$$

$$(b) [(t+1)u(t+1)] * \delta(t-2) = \boxed{(t-1)u(t-1)}$$

$$(c) \int_0^2 e^{-10\tau} \delta(\tau-3) d\tau = \boxed{\emptyset}$$

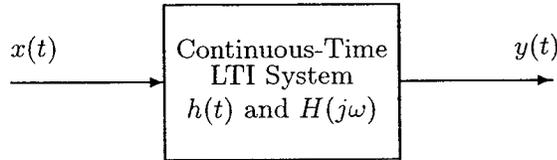
$$(d) x[n] = 5 \cos(0.3\pi n + \pi/2) + 5\sqrt{2} \cos(0.3\pi n - \pi/4) = \boxed{5 \cos(0.3\pi n)}$$

$$x[n] = \operatorname{Re} \left[(5e^{j\pi/2} + 5\sqrt{2} e^{-j\pi/4}) e^{j0.3\pi n} \right]$$

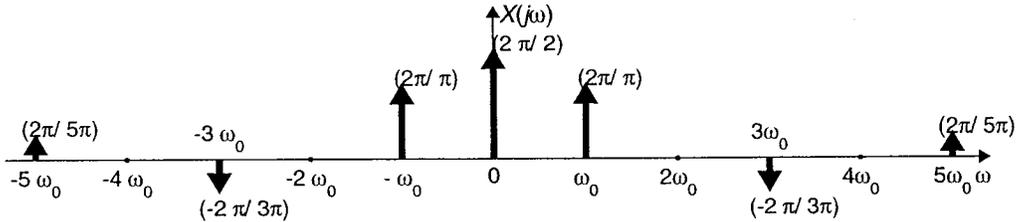
$$5e^{j\pi/2} + 5\sqrt{2} e^{-j\pi/4} = 5j + 5\sqrt{2} \left(\frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}}j \right) = 5$$

$$\Rightarrow x[n] = 5 \cos(0.3\pi n)$$

PROBLEM fall-04-F.2:



The periodic input to the above LTI system has the Fourier transform $X(j\omega)$ drawn below:



where the dark arrows denote impulses.

(a) If the frequency response of the filter is given by

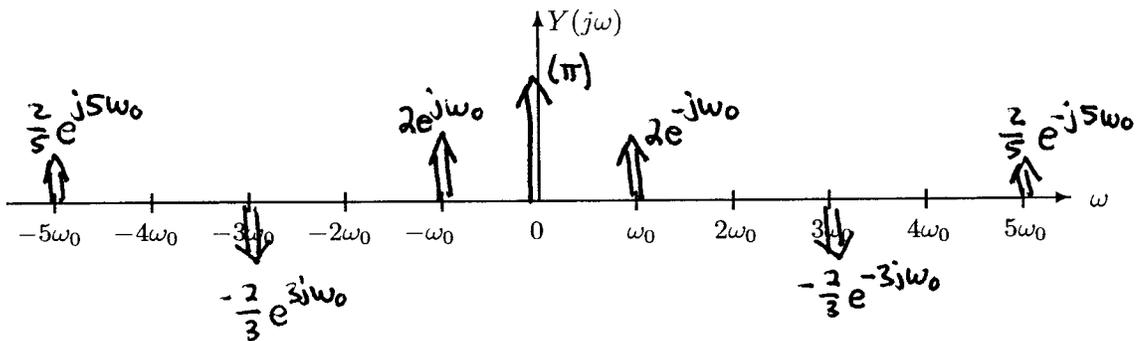
$$H(j\omega) = \begin{cases} e^{-2j\omega} & 5\omega_0/2 < |\omega| < 7\omega_0/2 \\ 0 & \text{otherwise} \end{cases}$$

determine $y(t)$. Your answer should be written as a real time function, i.e., there should be no j 's in your answer.

H(j\omega) is a bandpass filter that only passes the cosine at frequency $3\omega_0$. Since the filter has a delay of 2ω , then

$$y(t) = -\frac{2}{3\pi} \cos(3\omega_0(t-2))$$

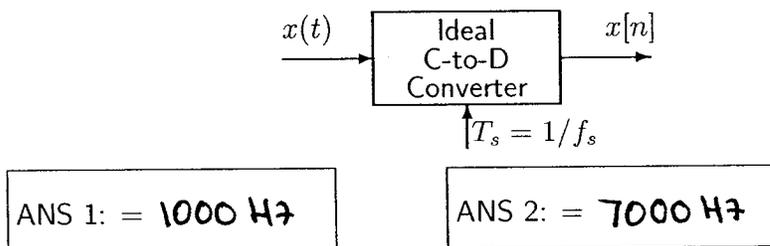
(b) If $y(t) = x(t - 1)$ sketch $Y(j\omega)$, the spectrum of $y(t)$, on the axes below.



PROBLEM fall-04-F.3:

The individual parts of this problem are independent.

- (a) If the output from an ideal C/D converter is $x[n] = 1000 \cos(0.25\pi n)$, and the sampling rate is 8000 samples/sec, then determine two possible positive values of the input frequency of $x(t)$ that are less than 8000 Hz.:



- (b) Suppose that a student writes the following MATLAB code to generate a sine wave:

```
nn = 0:44100;
xx = (3/pi) * cos(pi*1.25*nn + pi/3);
soundsc(xx, fsamp)
```

Although the sinusoid was not written to have a frequency of 2100 Hz, it is possible to play out the vector xx so that it sounds like a 2100 Hz tone. Determine the value of $fsamp$ that should be used to play the vector xx as a 2100 Hz tone. Write your answer as an integer.

fsamp = 5600

 Hz

$$\cos\left(\frac{5\pi}{4}n + \frac{\pi}{3}\right) = \cos\left(\frac{3\pi}{4}n - \frac{\pi}{3}\right)$$

$$\frac{3\pi}{4}f_s = 2100(2\pi) \Rightarrow f_s = \frac{2100(8)}{3} = 5600$$

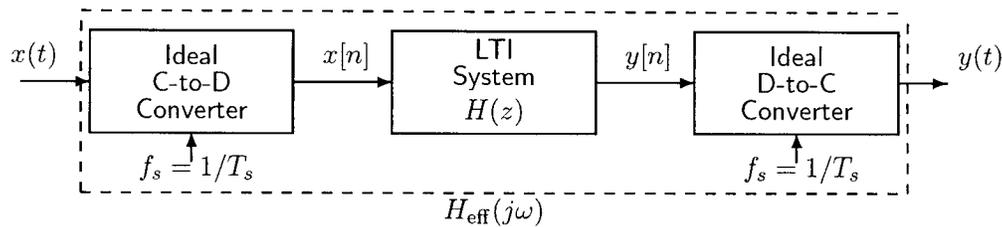
- (c) Determine the Nyquist rate for sampling the signal $x(t)$ defined by:
 $x(t) = \Re\{e^{j4000\pi t} + e^{-j3000\pi t}\}$.

ANS = 4000

 samples/sec.

PROBLEM fall-04-F.4:

Consider the following system for discrete-time filtering of a continuous-time signal:

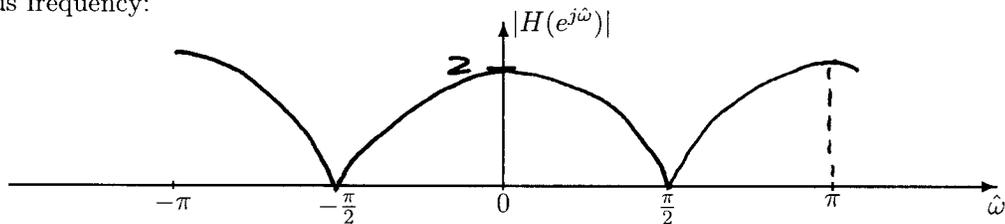


Assume that the discrete-time system is implemented using the MATLAB command:

```
yy=firfilt([0,0,1,0,1],xx)
```

where xx is an array of samples of $x[n]$ and yy holds samples of $y[n]$.

- (a) Determine the frequency response of the discrete-time filter and plot its magnitude response versus frequency:



$$H(e^{j\hat{\omega}}) = e^{-j2\hat{\omega}} + e^{-j4\hat{\omega}} = e^{-j3\hat{\omega}}(e^{j\hat{\omega}} + e^{-j\hat{\omega}})$$

$$= 2e^{-j3\hat{\omega}} \cos(\hat{\omega})$$

- (b) Assume that the input signal $x(t)$ is a sum of cosines:

$$x(t) = 3 \cos(100\pi t - \pi/4) + 2 \cos(400\pi t + \pi/3)$$

For this input signal, determine the output signal $y(t)$ when the sampling rate is $f_s = 300$ samples/sec. Your answer should be expressed as a sum of cosines.

$$x[n] = 3 \cos\left(\frac{100\pi n}{300} - \frac{\pi}{4}\right) + 2 \cos\left(\frac{400\pi n}{300} + \frac{\pi}{3}\right)$$

$$= 3 \cos\left(\frac{\pi n}{3} - \frac{\pi}{4}\right) + 2 \cos\left(\frac{4\pi}{3} n + \frac{\pi}{3}\right)$$

$$= 3 \cos\left(\frac{\pi}{3} n - \frac{\pi}{4}\right) + 2 \cos\left(\frac{2\pi}{3} n - \frac{\pi}{3}\right)$$

$$\Rightarrow y[n] = 3 \left(2 \cos\left(\frac{\pi}{3}\right)\right) \cos\left(\frac{\pi}{3} n - \pi - \frac{\pi}{4}\right) + 2 \left(2 \cos\left(\frac{2\pi}{3}\right)\right) \cos\left(\frac{2\pi}{3} n - 2\pi - \frac{\pi}{3}\right)$$

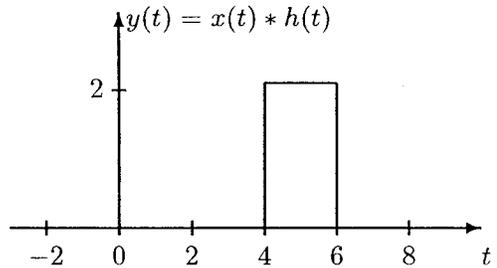
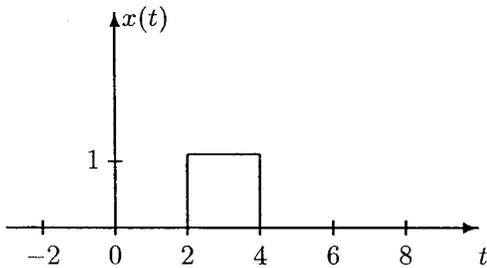
$$= 3 \cos\left(\frac{\pi}{3} n - \frac{5\pi}{4}\right) - 2 \cos\left(\frac{2\pi}{3} n - \frac{\pi}{3}\right)$$

$$y(t) = 3 \cos\left(100\pi t + \frac{3\pi}{4}\right) - 2 \cos\left(200\pi t - \frac{\pi}{3}\right)$$

PROBLEM fall-04-F.5:

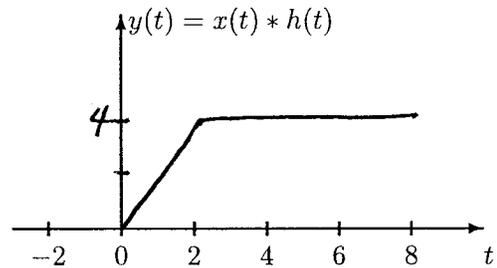
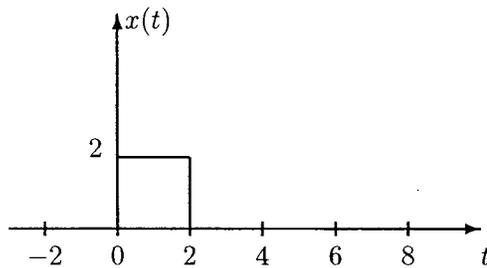
The parts of this problem are completely independent.

(a) Given that $y(t) = x(t) * h(t)$, find $h(t)$. $h(t) = 2\delta(t-2)$

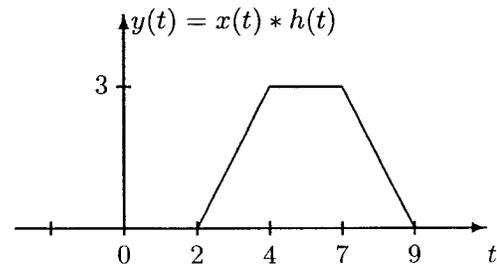
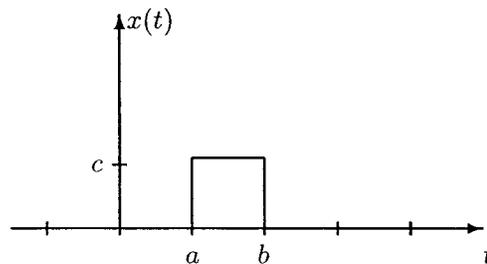


↑
delayed by two
scaled by two

(b) If $h(t) = u(t)$, plot $y(t) = x(t) * h(t)$ on the graph on the right. Be sure to label the $y(t)$ axis.



(c) If $h(t) = u(t-1) - u(t-3)$ and $y(t) = x(t) * h(t)$, determine the values of a , b , and c in the graph of $x(t)$ on the left, if $y(t)$ is given by the graph on the right.



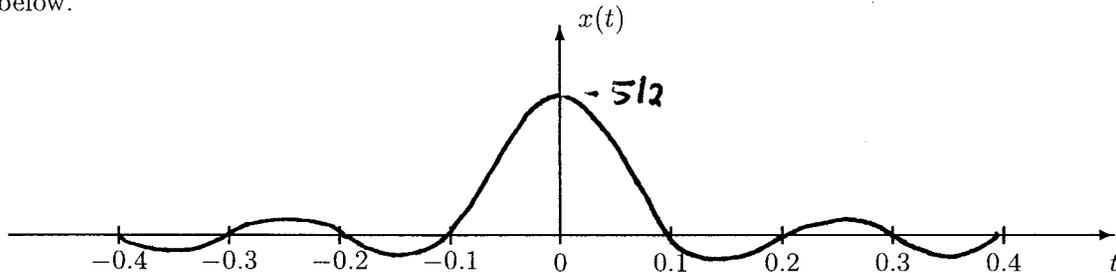
$a = 1$

$b = 6$

$c = 3/2$

PROBLEM fall-04-F.6:

- (a) Consider the signal $x(t) = \frac{\sin(10\pi t)}{4\pi t}$. Make a carefully labeled sketch of $x(t)$ in the space below.

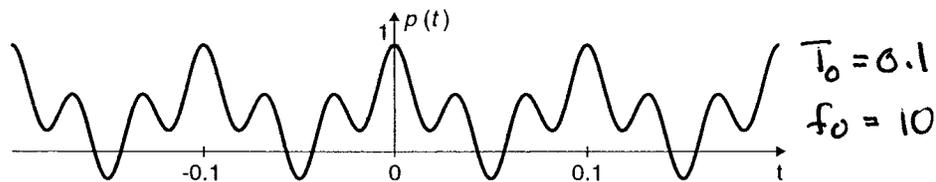


- (b) Determine the Fourier transform of $y(t) = x(2t - 0.2)$, using $x(t)$ from part (a).

$$y(t) = x(2t - 0.2) = \frac{\sin(10\pi(2t - 0.2))}{4\pi(2t - 0.2)} = \frac{\sin(20\pi(t - 0.1))}{8\pi(t - 0.1)}$$

$$\Rightarrow Y(j\omega) = \frac{1}{8} \left[u(\omega + 20\pi) - u(\omega - 20\pi) \right] e^{-j0.1\omega}$$

- (c) Now consider the periodic signal $p(t)$ plotted below:



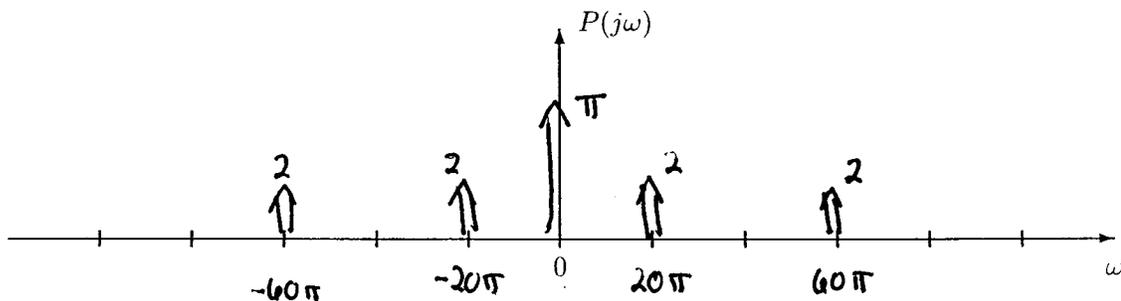
The Fourier series for this input can be simplified to the following form:

$$p(t) = \frac{1}{2} + \frac{2}{\pi} \cos(\omega_0 t) + \frac{2}{\pi} \cos(3\omega_0 t)$$

$\omega_0 = 20\pi \text{ rad/sec}$

First determine the value of ω_0 and put your result in the box. Then, either write an equation for $P(j\omega)$, the Fourier transform of $p(t)$, in the space below, or plot it on the axes below. You must label your plot carefully to receive full credit.

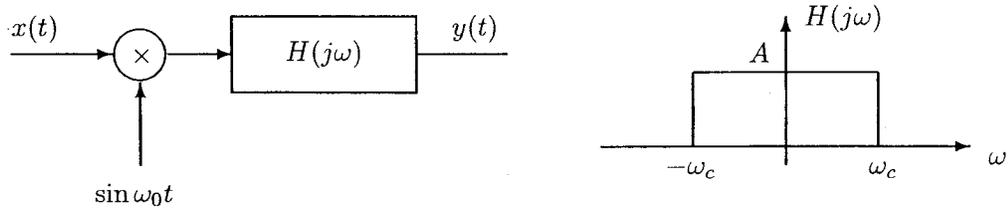
$$P(j\omega) = \pi + 2\delta(\omega - 20\pi) + 2\delta(\omega + 20\pi) + 2\delta(\omega - 60\pi) + 2\delta(\omega + 60\pi)$$



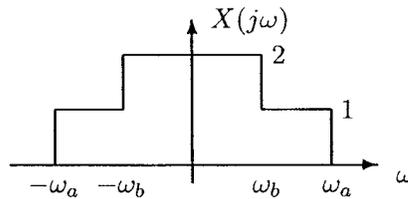
PROBLEM fall-04-F.7:

The two parts of this problem are independent.

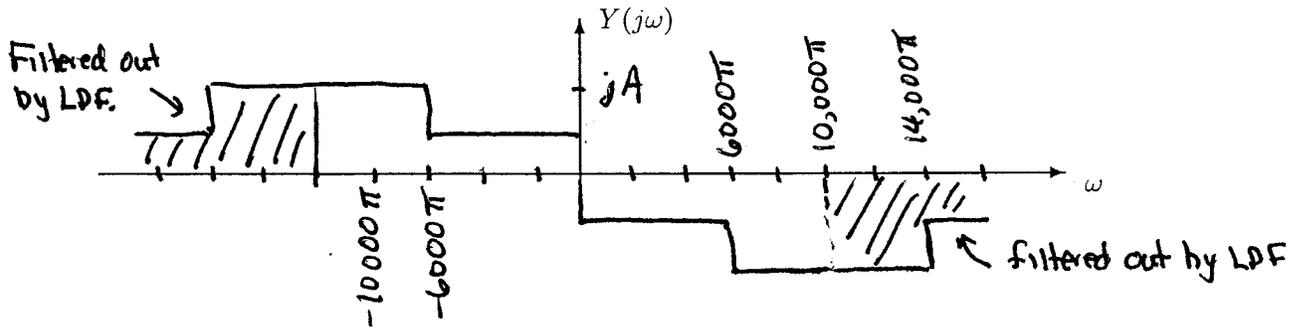
- (a) The system below is proposed as an alternative speech scrambler to the one in lab. Notice that the carrier signal is a sine instead of a cosine..



Assume that $x(t)$ has the spectrum, $X(j\omega)$ shown below

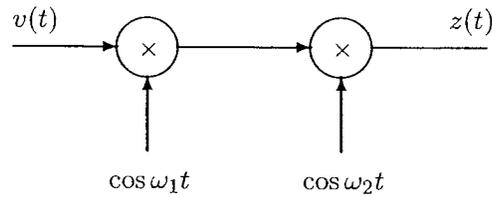


Sketch the spectrum, $Y(j\omega)$ of the output of the scrambler on the axes below if $\omega_a/(2\pi) = 5$ kHz, $\omega_b/(2\pi) = 2$ kHz, $\omega_c/(2\pi) = 5$ kHz, and $\omega_0/(2\pi) = 5$ kHz. Be sure to LABEL YOUR PLOT.

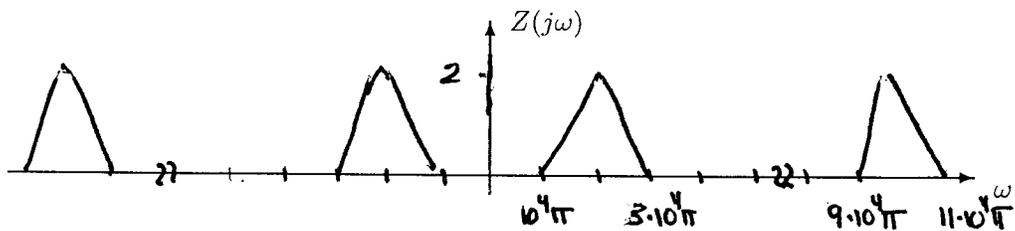
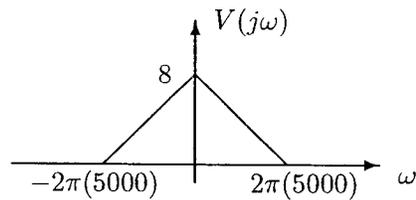


$$\sin \omega_0 t \longrightarrow -j\pi \delta(\omega - \omega_0) + j\pi \delta(\omega + \omega_0) \quad ; \quad \omega_0 = 10\pi$$

- (b) Signals are often repeatedly moved from one portion of the spectrum to another by repeated mixing. This process is called **heterodyning**. A simple example is the cascade of two mixers shown below.



Let $f_1 = \omega_1/(2\pi) = 30$ kHz and $f_2 = \omega_2/(2\pi) = 20$ kHz. Sketch the spectrum $Z(j\omega)$ assuming that $V(j\omega)$ has the shape shown in the figure below.



$$z(t) = v(t) \cdot \cos(\omega_1 t) \cdot \cos(\omega_2 t)$$

$$= \frac{1}{2} v(t) \left[\cos(\omega_1 + \omega_2)t + \cos(\omega_1 - \omega_2)t \right]$$

$$= \frac{1}{2} v(t) \left[\cos(20000\pi t) + \cos(100,000\pi t) \right]$$

PROBLEM fall-04-F.8:

A discrete-time system is defined by the following system function:

$$H(z) = H(z) = \frac{0.64 + z^{-2}}{1 - 0.64z^{-2}}$$

- (a) Write down the difference equation that is satisfied by the input $x[n]$ and output $y[n]$ of the system.

$$y[n] = 0.64y[n-2] + 0.64x[n] + x[n-2]$$

- (b) Fill in numbers for the vectors `bb` and `aa` in the following MATLAB computation of the frequency response of the system:

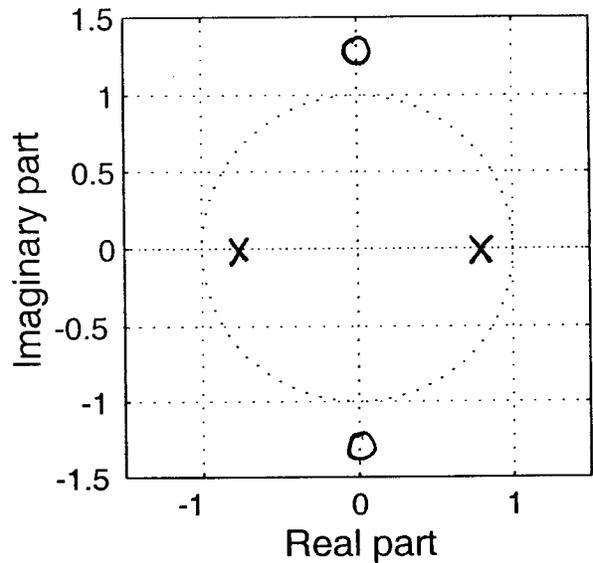
```
bb=[ 0.64, 0, 1 ];    aa=[ 1, 0, -0.64 ];
yy=filter(bb,aa,xx)
```

where `xx` is the input signal to be filtered.

- (c) Determine *all* the poles and zeros of $H(z)$ and plot them in the z -plane.

zeros: $z^{-2} = -0.64$
 $z = \pm j \frac{1}{0.8} = \pm j 1.25$

poles: $0.64z^{-2} = 1$
 $z^2 = 0.64$
 $z = \pm 0.8$



- (d) Make a sketch of the magnitude of the frequency response of the system over the range $-\pi < \omega \leq \pi$. Indicate where the peaks and valleys are located, and also determine the height of the peaks and the valleys.

